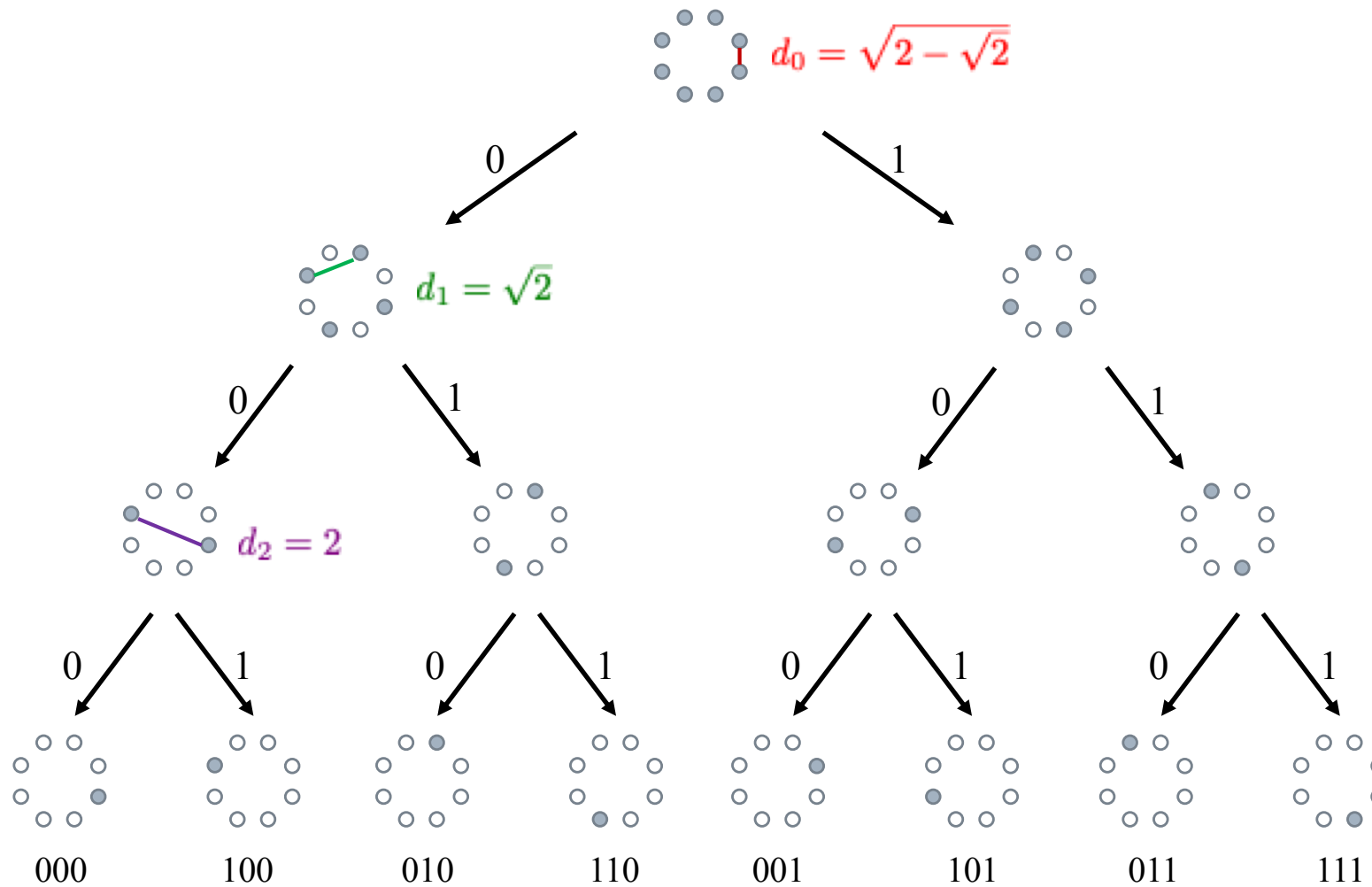

Part 8 Trellis Coded Modulation, Turbo Codes and LDPC Codes

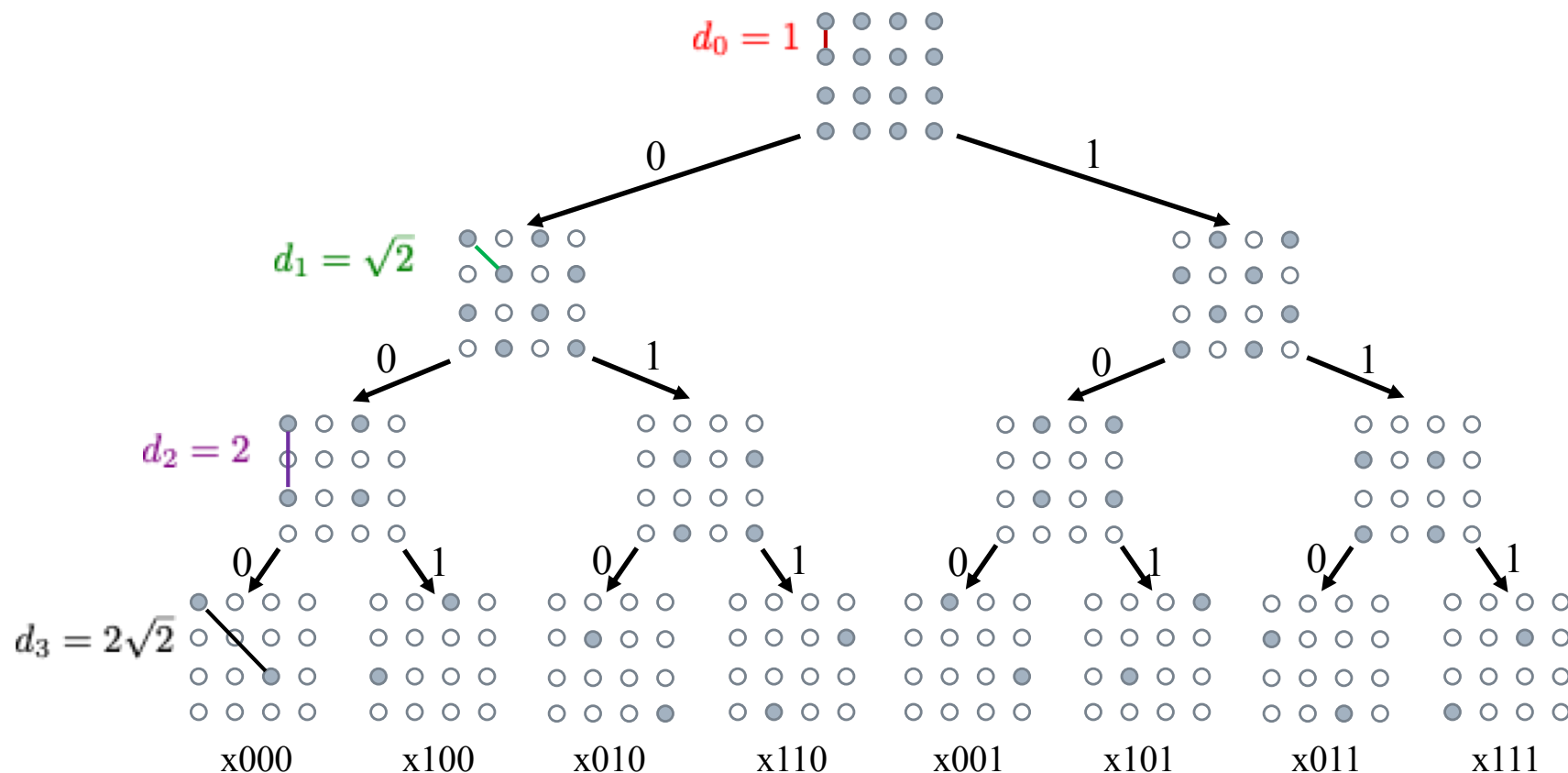
Trellis-Coded Modulation

- In the previous section, encoding is performed separately from modulation in the transmitter, and likewise for decoding and detection in the receiver.
- To attain more effective utilization of the available bandwidth and power, coding and modulation have to be treated as a single entity, e.g., **trellis-coded modulation**.
 - Instead of selecting codewords from “code bit domain”, we choose codewords from “signal constellation domain”.

Partitioning of 8-PSK constellation that shows $d_0 < d_1 < d_2$.



Partitioning of 16-QAM constellation that shows $d_0 < d_1 < d_2 < d_3$.



Trellis-Coded Modulation

□ Codeword versus code signal

0000

0011

1100

1111

Select 4 out of 16 possibilities

(The **bit** patterns are dependent **temporally** so that these **bit** patterns exhibit “error correcting capability”).)

0 π

$\frac{\pi}{2}$ $\frac{3\pi}{2}$

π 0

$\frac{3\pi}{2}$ $\frac{\pi}{2}$

Select 4 out of 16 possibilities from QPSK constellation

(The **signal** patterns are dependent **temporally** so these **signal** patterns exhibit “error correcting capability”).)

Trellis-Coded Modulation

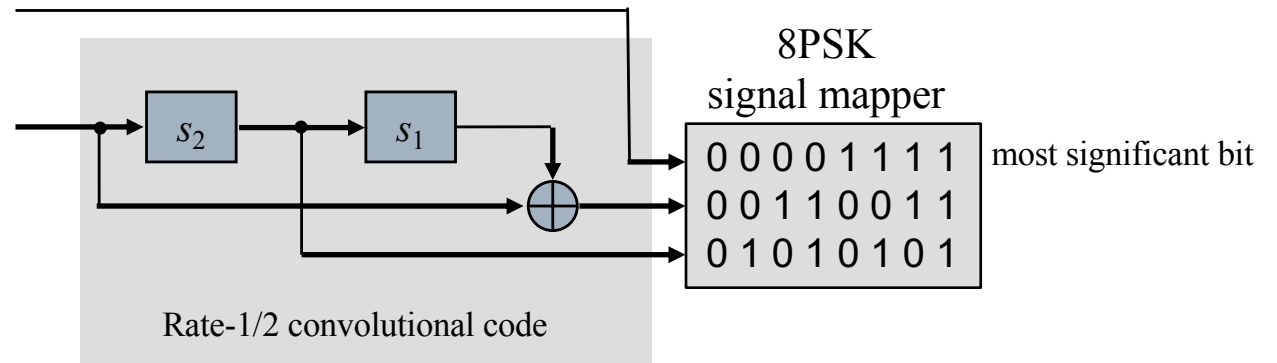
- Trellis codeword versus trellis code signal
 - The next **code bit** is a function of the current trellis state and some number of the previous **information bits**.
 - The next **code signal** is a function of the current trellis state and some number of the previous **information signals**.

□ Example of trellis-coded modulation

■ 4-state

Ungerboeck 8-PSK code

□ Code rate = 2 bits/symbol



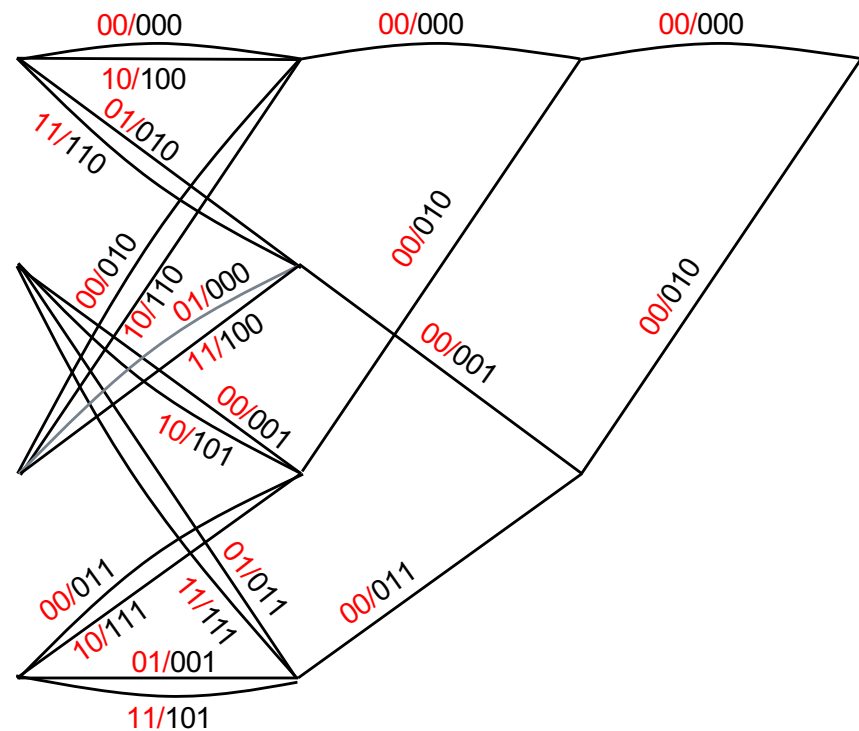
Encoder state

$s_2 s_1$
00

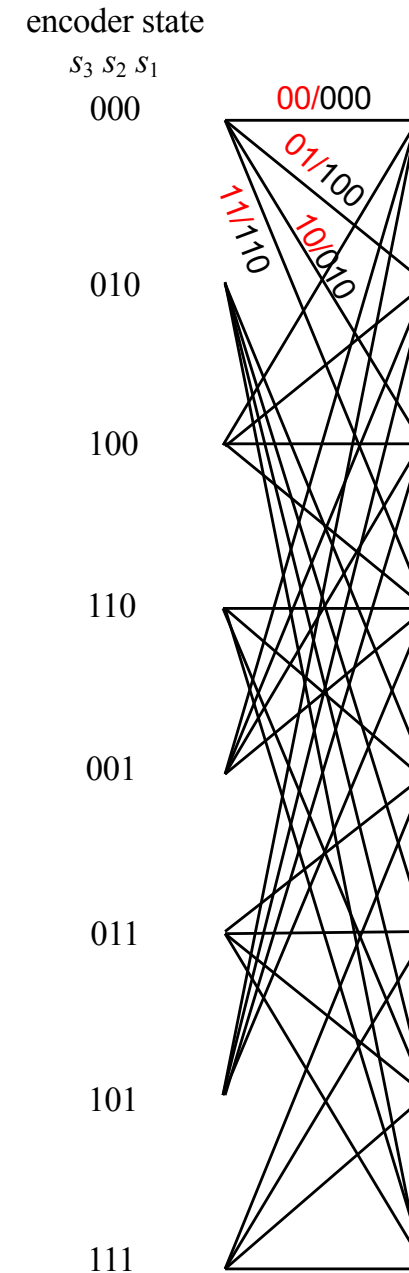
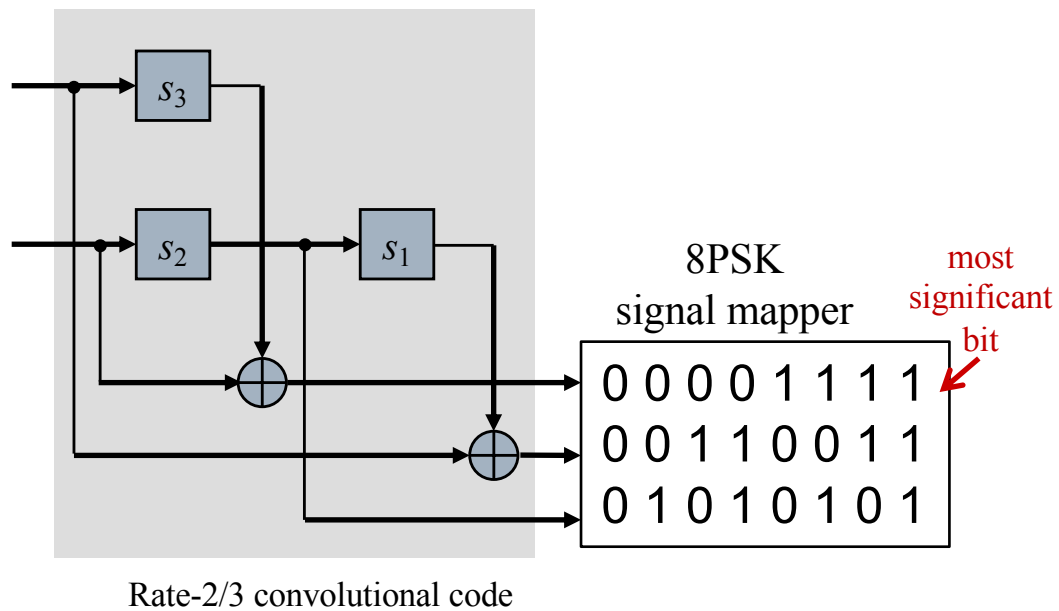
10

01

11



- Example of trellis-coded modulation
- 8-state Ungerboeck 8-PSK code
- Code rate = 2 bits/symbol



- Soft decision decoding (can be analyzed via an **equivalent** binary-input additive white Gaussian noise channel)
- The error rate of Ungerboeck codes (particularly at high SNR) is dominated by the “two codewords (i.e., signal words)” whose pairwise Euclidean distance is equal to d_{free} . (This d_{free} represents Euclidean distance, not the Hamming distance defined previously.)

\Rightarrow Equivalently $x_j = s_{j,m} + w_j$ for $j = 1, \dots, N$

$$\text{where } \|\mathbf{s}_0 - \mathbf{s}_1\|^2 = \sum_{j=1}^N (s_{j,0} - s_{j,1})^2 = d_{\text{free}}^2$$

$$\Rightarrow \hat{m} = \arg \max \{P(\mathbf{x} | \mathbf{s}_0), P(\mathbf{x} | \mathbf{s}_1)\}$$

$$\Rightarrow \hat{m} = \arg \max \left\{ \prod_{j=1}^N e^{-(x_j - s_{j,0})^2 / 2\sigma^2}, \prod_{j=1}^N e^{-(x_j - s_{j,1})^2 / 2\sigma^2} \right\}$$

$$\Rightarrow \|\mathbf{x} - \mathbf{s}_0\|^2 \underset{\mathbf{s}_1}{\overset{\mathbf{s}_0}{\leq}} \|\mathbf{x} - \mathbf{s}_1\|^2 \quad \mathbf{x} \begin{cases} \mathcal{N}(\mathbf{s}_0, \sigma^2 \mathbb{I}) & \mathbf{s}_0 \text{ transmitted} \\ \mathcal{N}(\mathbf{s}_1, \sigma^2 \mathbb{I}) & \mathbf{s}_1 \text{ transmitted} \end{cases}$$

■ Based on the decision rule $\|\mathbf{x} - \mathbf{s}_0\|^2 \underset{\mathbf{s}_1}{\overset{\mathbf{s}_0}{\leq}} \|\mathbf{x} - \mathbf{s}_1\|^2$

Dominant pairwise error

$$\begin{aligned} &= P(\mathbf{s}_0 \text{ transmitted}) P(\|\mathbf{x} - \mathbf{s}_0\|^2 > \|\mathbf{x} - \mathbf{s}_1\|^2 | \mathbf{s}_0 \text{ transmitted}) \\ &\quad + P(\mathbf{s}_1 \text{ transmitted}) P(\|\mathbf{x} - \mathbf{s}_0\|^2 < \|\mathbf{x} - \mathbf{s}_1\|^2 | \mathbf{s}_1 \text{ transmitted}) \\ &= P(\|\mathbf{x} - \mathbf{s}_0\|^2 > \|\mathbf{x} - \mathbf{s}_1\|^2 | \mathbf{s}_0 \text{ transmitted}) \\ &= P(\|\mathbf{w}\|^2 > \|\mathbf{w} + \mathbf{s}_0 - \mathbf{s}_1\|^2), \text{ where } \mathbf{x} = \mathbf{s}_0 + \mathbf{w} \\ &= P\left(\langle \mathbf{w}, \mathbf{s}_0 - \mathbf{s}_1 \rangle < -\frac{1}{2} \|\mathbf{s}_0 - \mathbf{s}_1\|^2\right) \quad \begin{matrix} \langle \mathbf{w}, \mathbf{s}_0 - \mathbf{s}_1 \rangle \\ \sim \mathcal{N}(0, \|\mathbf{s}_0 - \mathbf{s}_1\|^2 \sigma^2) \end{matrix} \\ &= \Phi\left(\frac{-\frac{1}{2} \|\mathbf{s}_0 - \mathbf{s}_1\|^2 - 0}{\|\mathbf{s}_0 - \mathbf{s}_1\| \sigma}\right) = \Phi\left(-\frac{d_{\text{free}}}{2\sigma}\right) \leq \exp\{-d_{\text{free}}^2/(4N_0)\} \end{aligned}$$

$$\Phi(-x) = \frac{1}{2} \text{erfc}\left(\frac{x}{\sqrt{2}}\right) \leq \frac{1}{x\sqrt{2\pi}} e^{-x^2/2} \leq e^{-x^2/2} \text{ for } x > 1/\sqrt{2\pi}$$

$$\sigma^2 = N_0/2$$

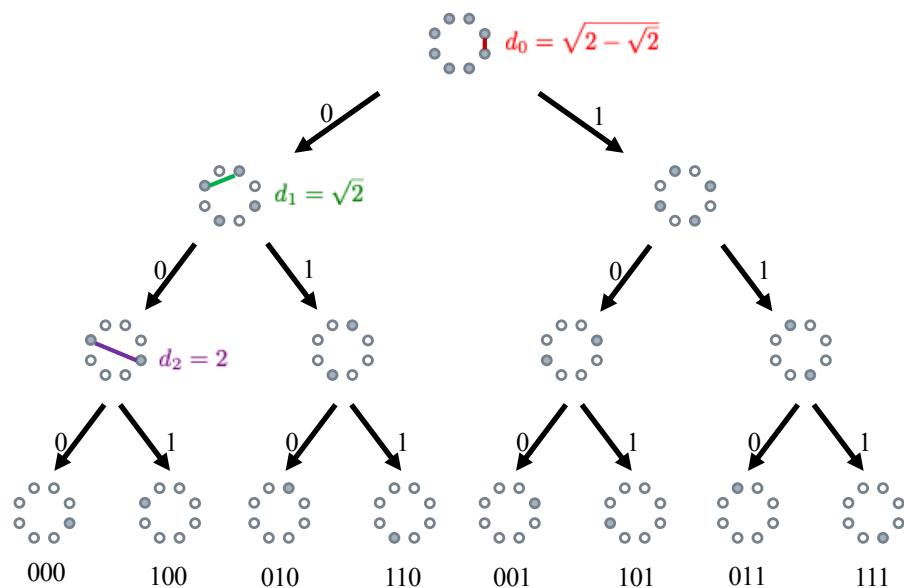
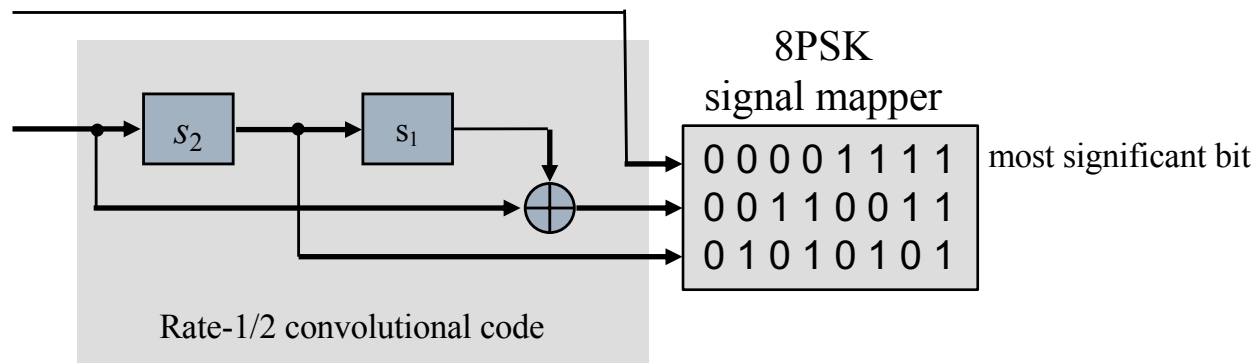
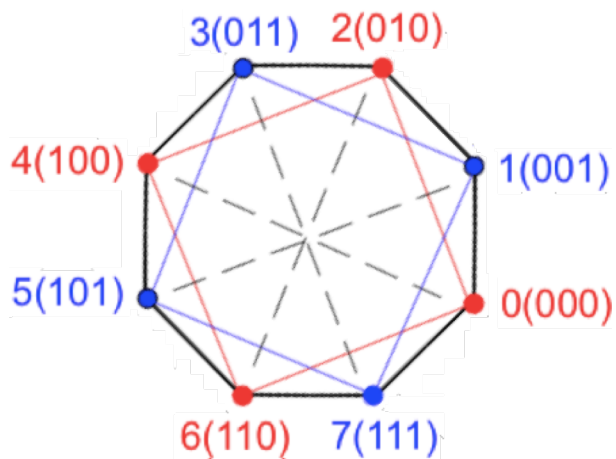
- Asymptotic coding gain (here, asymptotic = at high SNR) G_a
 - The performance gain due to coding (i.e., the performance gain of a coded system against an uncoded system)

$$\text{Uncoded } \exp \left\{ -d_{\text{ref}}^2 / (4N_0) \right\}$$

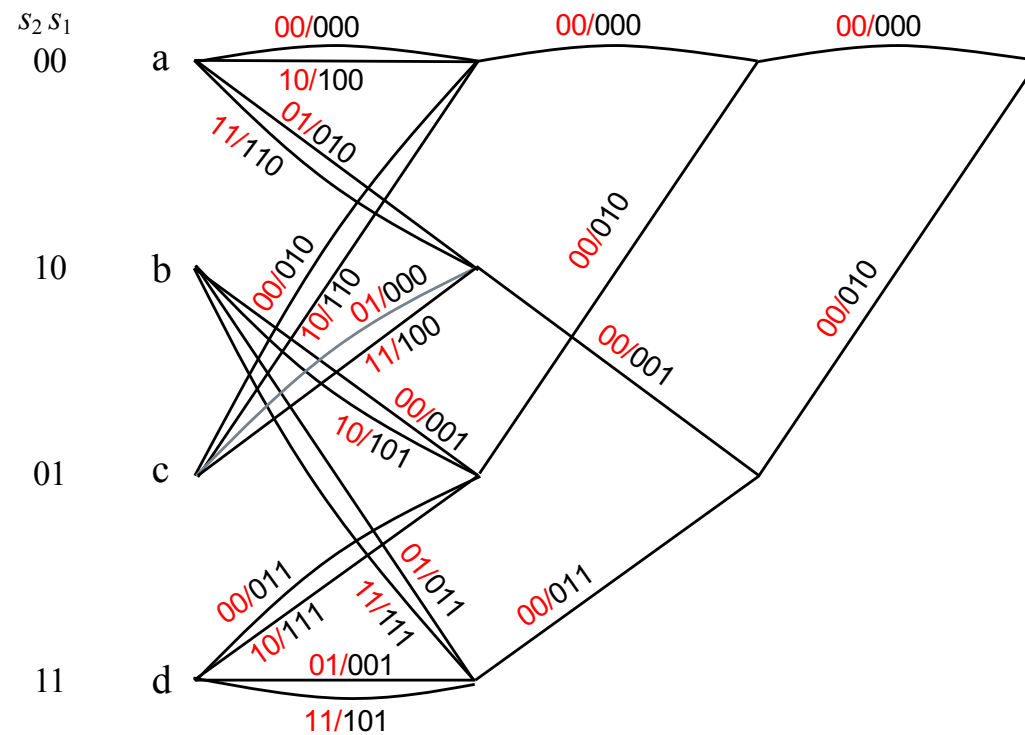
$$\text{Coded system } \exp \left\{ -d_{\text{free}}^2 / (4N_0) \right\}$$

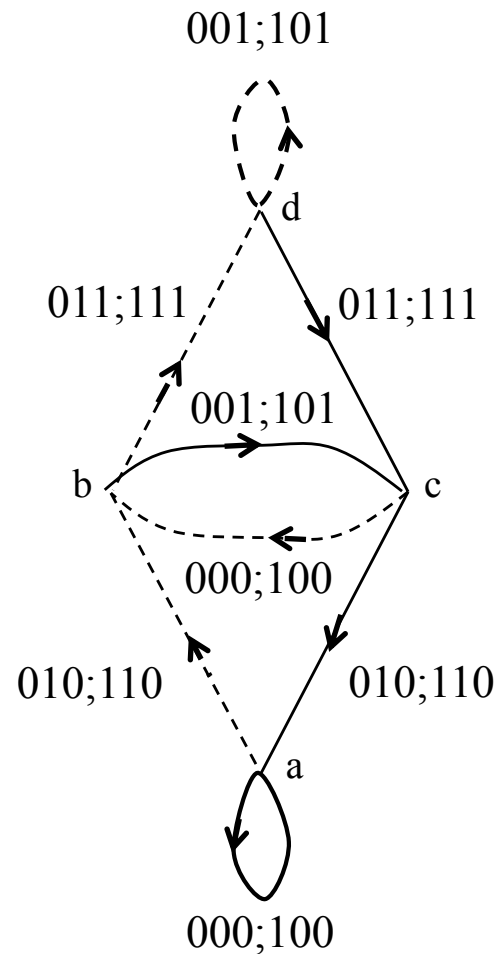
$$G_a = 10 \log_{10} \left(\frac{d_{\text{free}}^2}{d_{\text{ref}}^2} \right)$$

- 4-state Ungerboeck code
 - Its code rate is 2 bits/symbol; hence, it should be compared with uncoded QPSK.

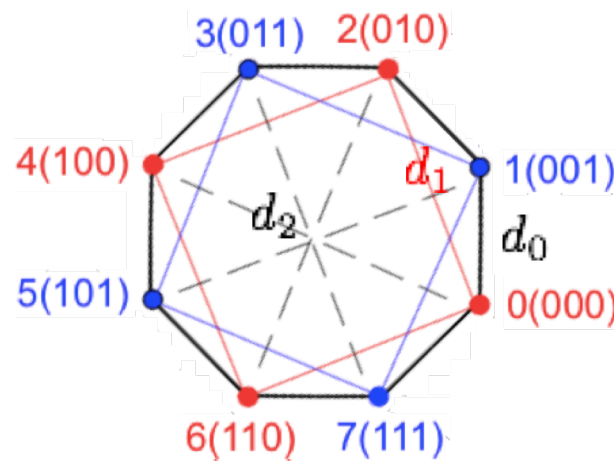
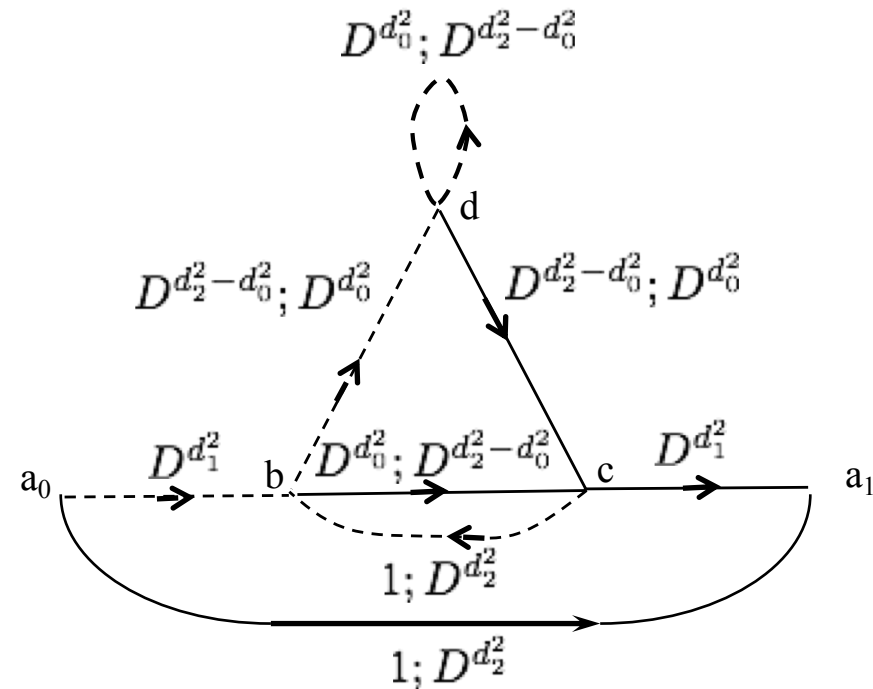
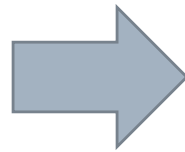


Encoder state





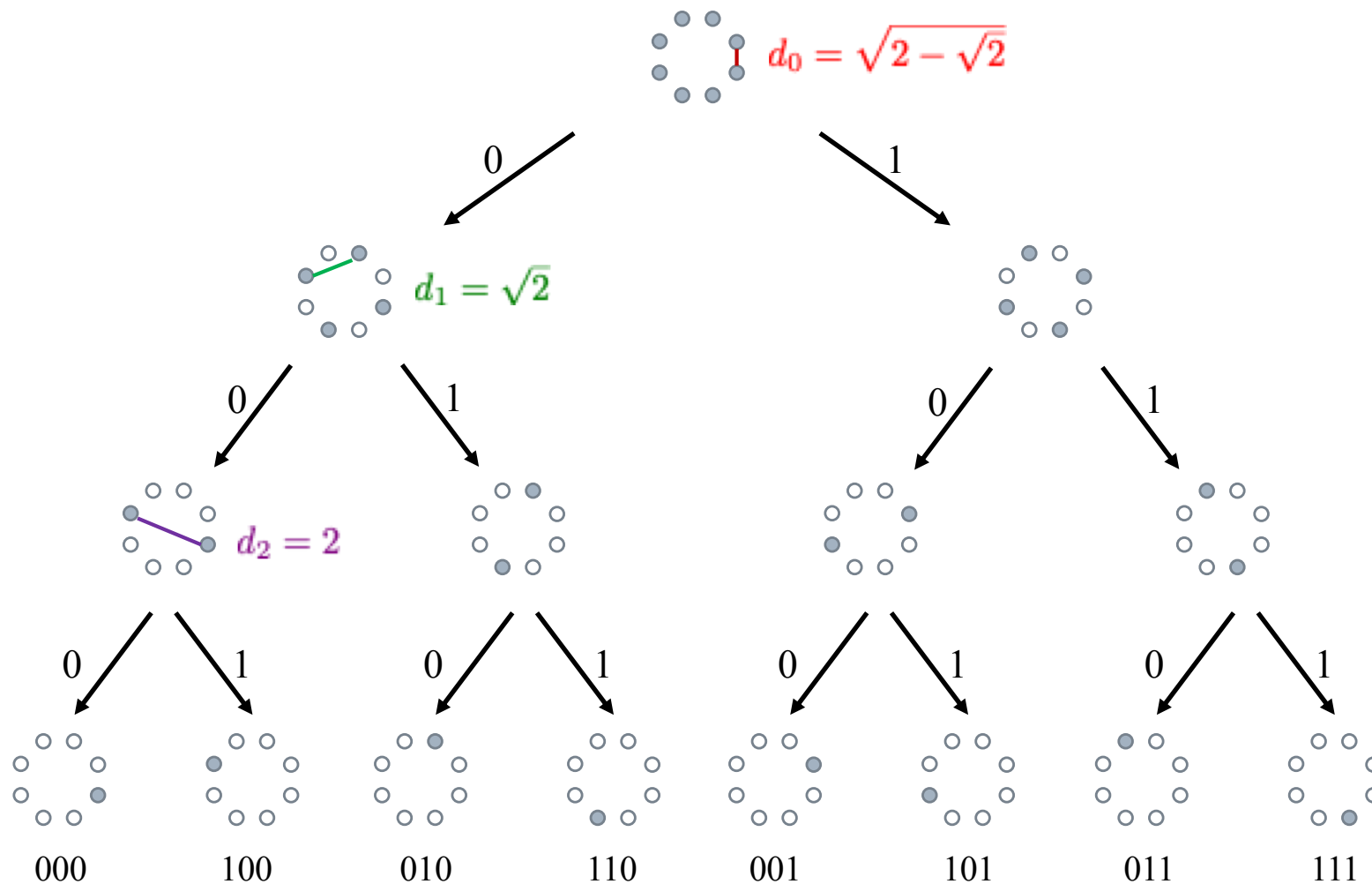
Solid line : 00;10
Dashed line : 01;11



Hence, $d_{\text{free}} = d_2$.

See the example in the next slide with three input signals plus two zero tail signals.

Signals	Code signals	Distance square to "all-zero" signals	Signals	Code signals	Distance square to "all-zero" signals
00 00 00	000 000 000 000 000	0	01 00 00	010 001 010 000 000	$2d_1^2 + d_0^2$
00 00 10	000 000 100 000 000	d_2^2	01 00 10	010 001 110 000 000	$2d_1^2 + d_0^2$
00 00 01	000 000 010 001 010	$2d_1^2 + d_0^2$	01 00 01	010 001 000 001 010	$2d_1^2 + 2d_0^2$
00 00 11	000 000 110 001 010	$2d_1^2 + d_0^2$	01 00 11	010 001 100 001 010	$d_2^2 + 2d_1^2 + 2d_0^2$
00 10 00	000 100 000 000 000	d_2^2	01 10 00	010 101 010 000 000	$2d_1^2 + (d_2^2 - d_0^2)$
00 10 10	000 100 100 000 000	$2d_2^2$	01 10 10	010 101 110 000 000	$2d_1^2 + (d_2^2 - d_0^2)$
00 10 01	000 100 010 001 010	$d_2^2 + 2d_1^2 + d_0^2$	01 10 01	010 101 000 001 010	$2d_1^2 + (d_2^2 - d_0^2) + d_0^2$
00 10 11	000 100 110 001 010	$d_2^2 + 2d_1^2 + d_0^2$	01 10 11	010 101 100 001 010	$d_2^2 + 2d_1^2 + (d_2^2 - d_0^2) + d_0^2$
00 01 00	000 010 001 010 000	$2d_1^2 + d_0^2$	01 01 00	010 011 011 001 000	$d_1^2 + 2(d_2^2 - d_0^2) + d_0^2$
00 01 10	000 010 101 010 000	$2d_1^2 + (d_2^2 - d_0^2)$	01 01 10	010 011 111 001 000	$d_1^2 + (d_2^2 - d_0^2) + 2d_0^2$
00 01 01	000 010 011 011 010	$2d_1^2 + 2(d_2^2 - d_0^2)$	01 01 01	010 011 001 011 010	$2d_1^2 + 2(d_2^2 - d_0^2) + d_0^2$
00 01 11	000 010 111 011 010	$2d_1^2 + (d_2^2 - d_0^2) + d_0^2$	01 01 11	010 011 101 011 010	$2d_1^2 + 3(d_2^2 - d_0^2)$
00 11 00	000 110 001 010 000	$2d_1^2 + d_0^2$	01 11 00	010 111 011 010 000	$2d_1^2 + d_0^2 + (d_2^2 - d_0^2)$
00 11 10	000 110 101 010 000	$2d_1^2 + (d_2^2 - d_0^2)$	01 11 10	010 111 111 010 000	$2d_1^2 + 2d_0^2$
00 11 01	000 110 011 011 010	$2d_1^2 + 2(d_2^2 - d_0^2)$	01 11 01	010 111 001 011 010	$2d_1^2 + 2d_0^2 + (d_2^2 - d_0^2)$
00 11 11	000 110 111 011 010	$2d_1^2 + (d_2^2 - d_0^2) + d_0^2$	01 11 11	010 111 101 011 010	$2d_1^2 + d_0^2 + 2(d_2^2 - d_0^2)$
10 00 00	100 000 000 000 000	d_2^2	11 00 00	110 001 010 000 000	$2d_1^2 + d_0^2$
10 00 10	100 000 100 000 000	$2d_2^2$	11 00 10	110 001 110 000 000	$2d_1^2 + d_0^2$
10 00 01	100 000 010 001 010	$d_2^2 + 2d_1^2 + d_0^2$	11 00 01	110 001 000 001 010	$2d_1^2 + 2d_0^2$
10 00 11	100 000 110 001 010	$d_2^2 + 2d_1^2 + d_0^2$	11 00 11	110 001 100 001 010	$d_2^2 + 2d_1^2 + 2d_0^2$
10 10 00	100 100 000 000 000	$2d_2^2$	11 10 00	110 101 010 000 000	$2d_1^2 + (d_2^2 - d_0^2)$
10 10 10	100 100 100 000 000	$3d_2^2$	11 10 10	110 101 110 000 000	$2d_1^2 + (d_2^2 - d_0^2)$
10 10 01	100 100 010 001 010	$2d_2^2 + 2d_1^2 + d_0^2$	11 10 01	110 101 000 001 010	$2d_1^2 + (d_2^2 - d_0^2) + d_0^2$
10 10 11	100 100 110 001 010	$2d_2^2 + 2d_1^2 + d_0^2$	11 10 11	110 101 100 001 010	$d_2^2 + 2d_1^2 + (d_2^2 - d_0^2) + d_0^2$
10 01 00	100 010 001 001 000	$d_2^2 + d_1^2 + 2d_0^2$	11 01 00	110 011 011 010 000	$2d_1^2 + 2(d_2^2 - d_0^2)$
10 01 10	100 010 101 001 000	$d_2^2 + d_1^2 + (d_2^2 - d_0^2) + d_0^2$	11 01 10	110 011 111 010 000	$2d_1^2 + (d_2^2 - d_0^2) + d_0^2$
10 01 01	100 010 011 011 010	$d_2^2 + 2d_1^2 + 2(d_2^2 - d_0^2)$	11 01 01	110 011 001 011 010	$2d_1^2 + 2(d_2^2 - d_0^2) + d_0^2$
10 01 11	100 010 111 011 010	$d_2^2 + 2d_1^2 + d_0^2 + (d_2^2 - d_0^2)$	11 01 11	110 011 101 011 010	$2d_1^2 + 3(d_2^2 - d_0^2)$
10 11 00	100 110 001 010 000	$d_2^2 + 2d_1^2 + d_0^2$	11 11 00	110 111 011 001 010	$2d_1^2 + 2d_0^2 + (d_2^2 - d_0^2)$
10 11 10	100 110 101 001 000	$d_2^2 + d_1^2 + (d_2^2 - d_0^2) + d_0^2$	11 11 10	110 111 111 001 010	$2d_1^2 + 3d_0^2$
10 11 01	100 110 011 011 010	$d_2^2 + d_1^2 + 2(d_2^2 - d_0^2) + d_1^2$	11 11 01	110 111 001 011 010	$2d_1^2 + 2d_0^2 + (d_2^2 - d_0^2)$
10 11 11	100 110 111 011 010	$d_2^2 + 2d_1^2 + d_0^2 + (d_2^2 - d_0^2)$	11 11 11	110 111 101 011 010	$2d_1^2 + d_0^2 + 2(d_2^2 - d_0^2)$



$$\begin{aligned} d_{\text{free}} &= d_2 = 2 \\ d_{\text{ref}} &= d_1 = \sqrt{2} \end{aligned} \Rightarrow G_a = 10 \log_{10} \left(\frac{d_{\text{free}}^2}{d_{\text{ref}}^2} \right) = 3 \text{ dB}$$

□ Final note

- Asymptotic coding gain of Ungerboeck codes increases as the number of states grows.

Number of states	4	8	16	32	64	128	256	512
Coding gain (dB)	3	3.6	4.1	4.6	4.8	5	5.4	5.7

References

- [1] Gottfried Ungerboeck, “Channel coding with multilevel/phase signals,” *IEEE Trans, Inf. Theory*, vol. IT-28, no. 1, pp. 55-67, Jan. 1982.
- [2] -----, “Trellis-coded modulation with redundant signal sets part I: Introduction,” *IEEE Comm. Magazine*, vol. 25, no. 2, pp. 5-11, Feb. 1987.
- [3] -----, “Trellis-coded modulation with redundant signal sets part II: State of the art,” *IEEE Comm. Magazine*, vol. 25, no. 2, pp. 12-21, Feb. 1987.

Turbo Codes

- The birth of turbo coding
 - Year: 1993
 - Authors: Berrou, Glavieux and Thitimajshima
 - Paper Title: Near Shannon Limit Error-Correcting Coding and Decoding: Turbo Codes
 - Place: International Conference on Communications (ICC'93) in Geneva

Turbo Codes

- Autobiography of the inventors

- Claude Berrou

- Born in France in 1951

- Received the electrical engineering degree from the Institut National Polytechnique, Grenoble, France, in 1975

- Joined France Telecom University in 1978

- Alain Glavieux

- Born in France in 1949

- Received the engineering degree from the Ecole Nationale Supérieure des Telecommunications, Paris, France, in 1978

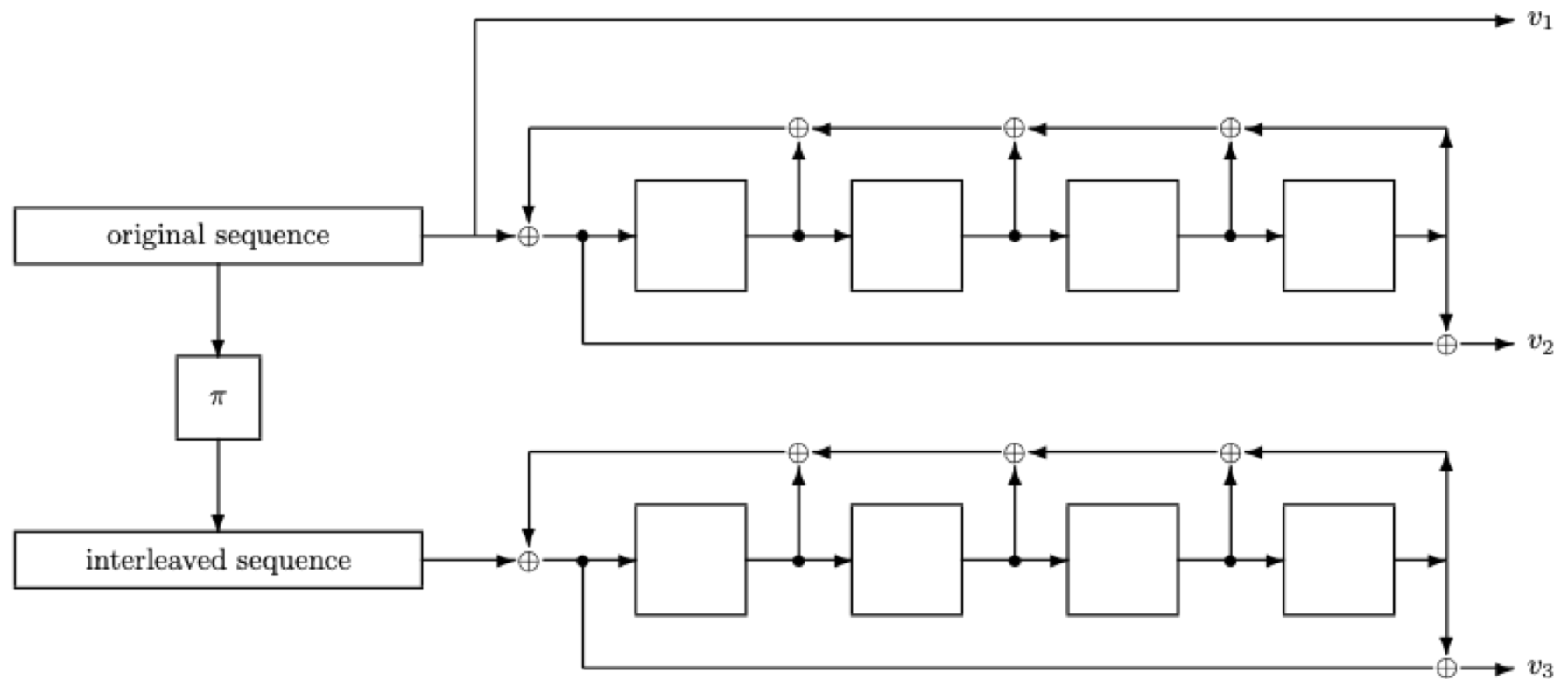
- Joined France Telecom University in 1979

- P. Thitimajshima

- Received Ph.D. degree in 1993

Turbo Codes

□ Structure of the turbo code encoder



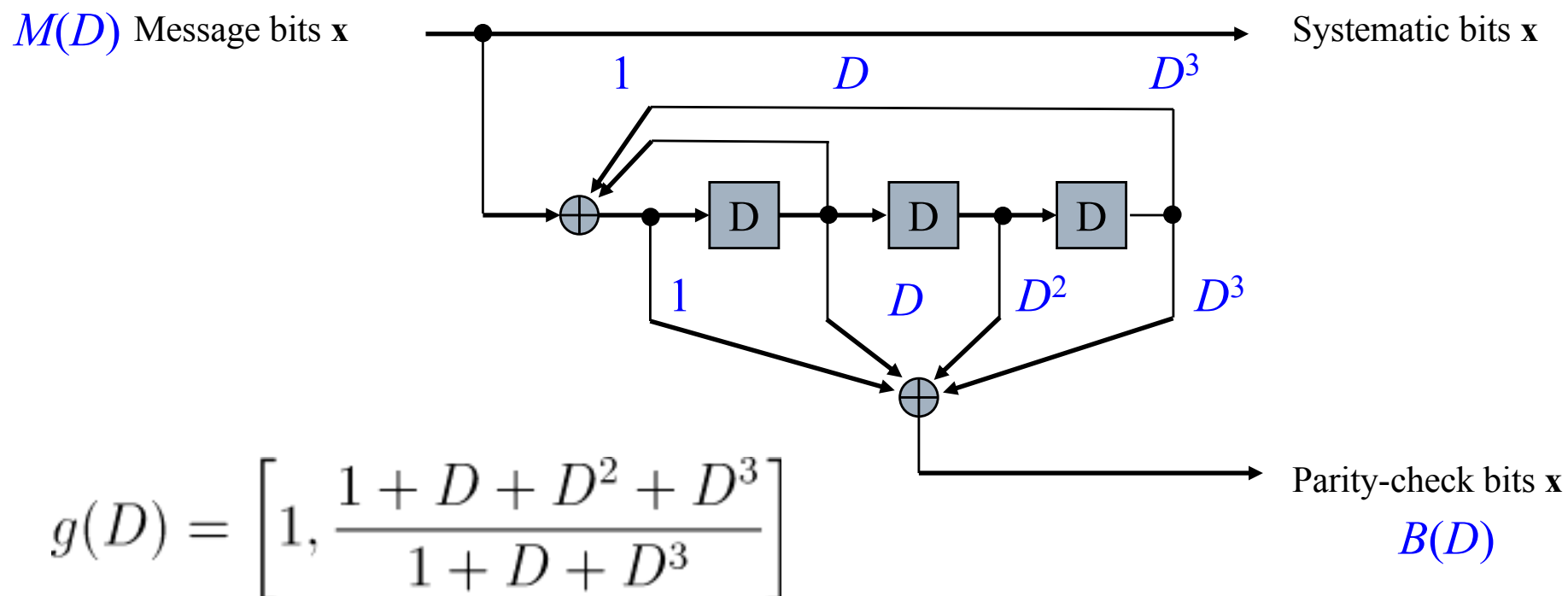
Turbo Codes

□ Basic considerations

- Add an interleaver to tie together distant bits.
- Use *recursive* systematic convolutional (RSC) codes to make the *internal state depend on the past outputs*.
- Use recursive *systematic* convolutional (RSC) codes to make the *turbo-like iterative decoding possible*.
 - RSC code may suffer *catastrophic error propagation* (one single output error produces an infinite number of parity errors).
- Use *short constraint-length* RSC codes to *reduce to decoding burden in each decoding iteration*.

Turbo Codes

□ Example: Eight-state RSC (constituent) encoder



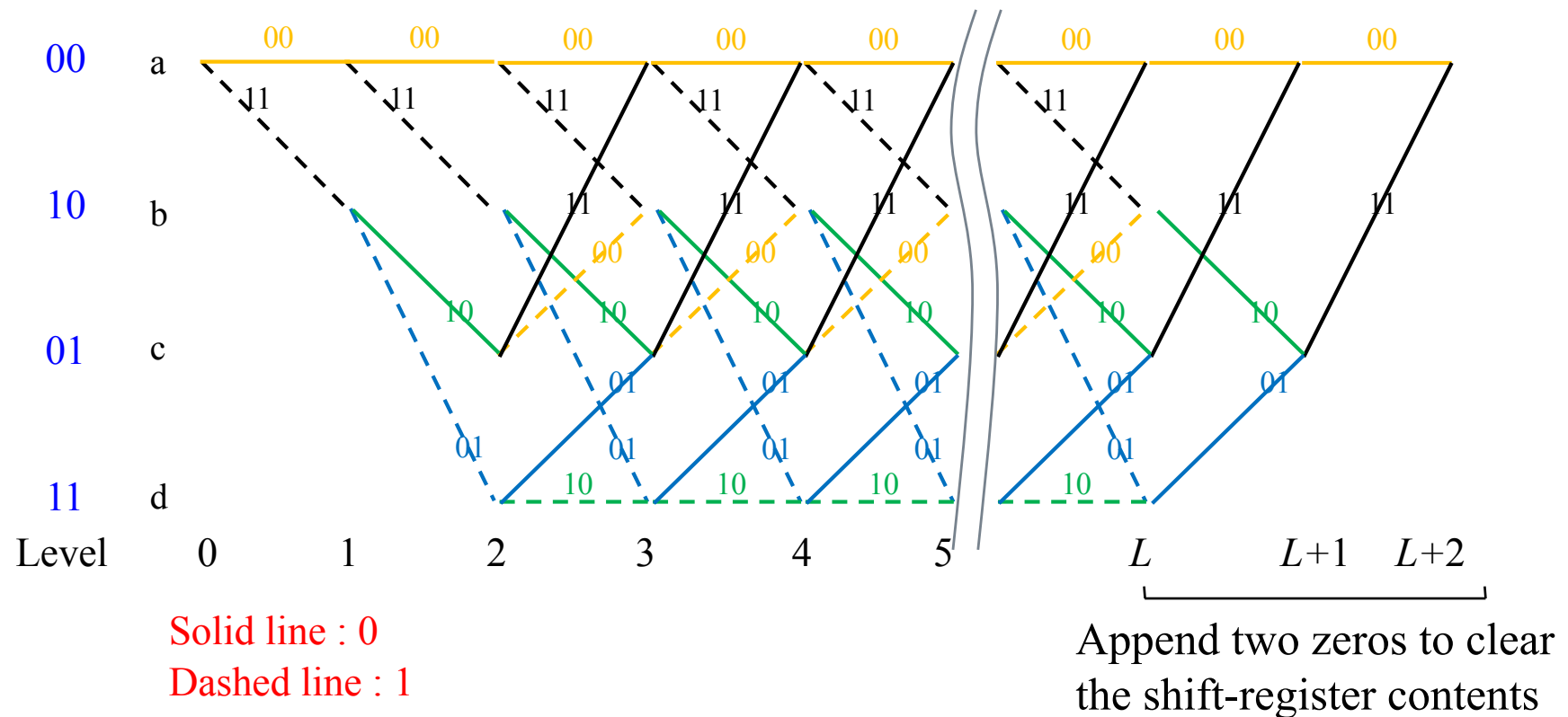
Turbo Codes

$$\frac{B(D)}{M(D)} = \frac{1 + D + D^2 + D^3}{1 + D + D^3}$$

$$\Rightarrow b_i = m_i + m_{i-1} + m_{i-2} + m_{i-3} - b_{i-1} - b_{i-3}$$

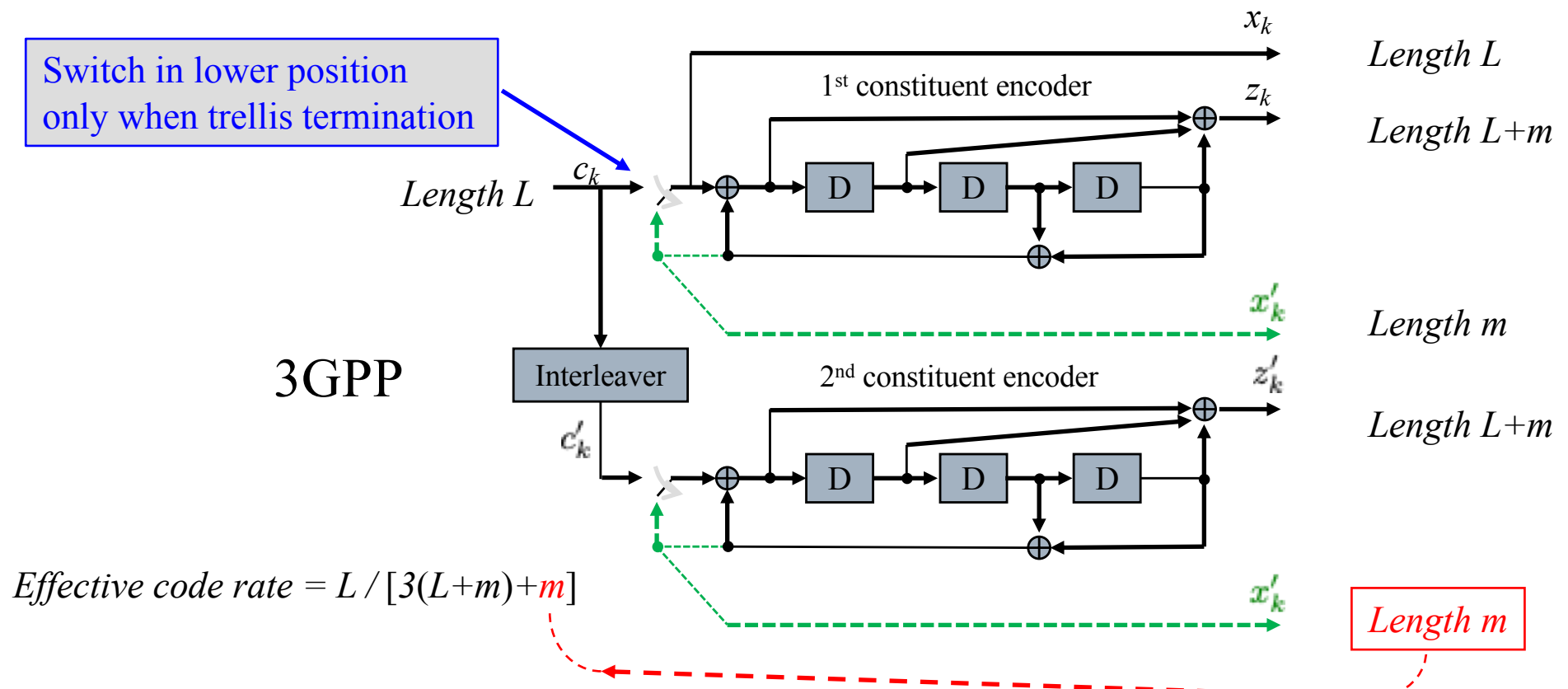
□ Remark 1: Zero tail bits

- With the pseudo-random interleaver, the zero tail bits for the first encoder may not appear to be the tail bits of the second encoder.

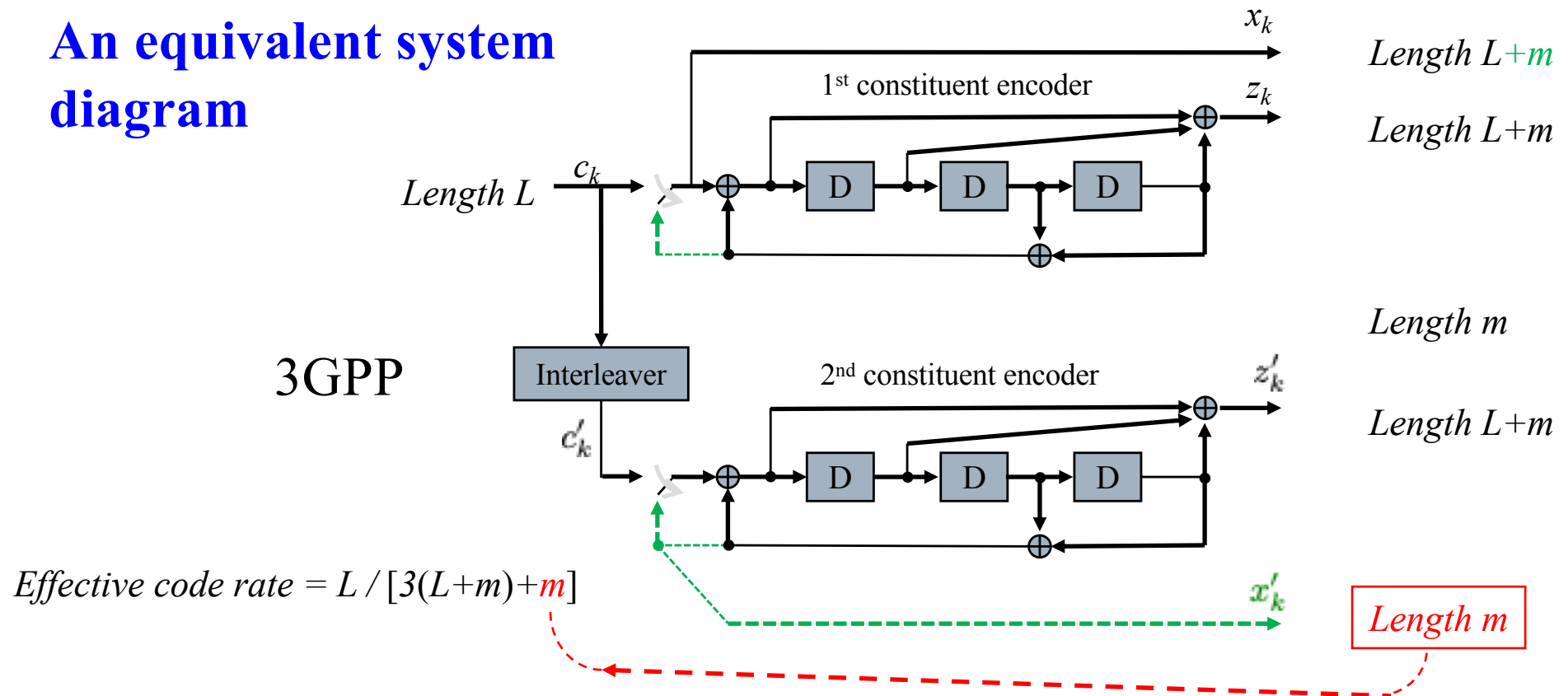


□ Remark 1: Zero tail bits (continue)

- With a careful design, dual clearing of the two encoder register contents can be achieved, which results in considerable performance improvement at medium to high SNRs.



An equivalent system diagram



□ Remark 2: Punctured convolution code.

- Each (2, 1) constituent encoder generates $L+m$ parity-check bits. With two constituent encoders, the system transmits $3L+4m$ bits, which reduces the code rate to approximately $1/3$.

□ Remark 2: Punctured convolution code (continue)

- To improve the code rate, one can “puncture” half of the parity-check bits generated by each constituent encoder.
- With two constituent encoders, the system transmits L information bits and approximately $L = (L/2) * 2$ parity-check bits, which reduces the code rate to around $1/2$.
- At the decoder side, since we exactly know that “no transmission” is performed in those punctured positions, we can directly “nullify” (i.e., make them zero) the corresponding received scalars.
- For example,

x_1 and x_2 are information bits.

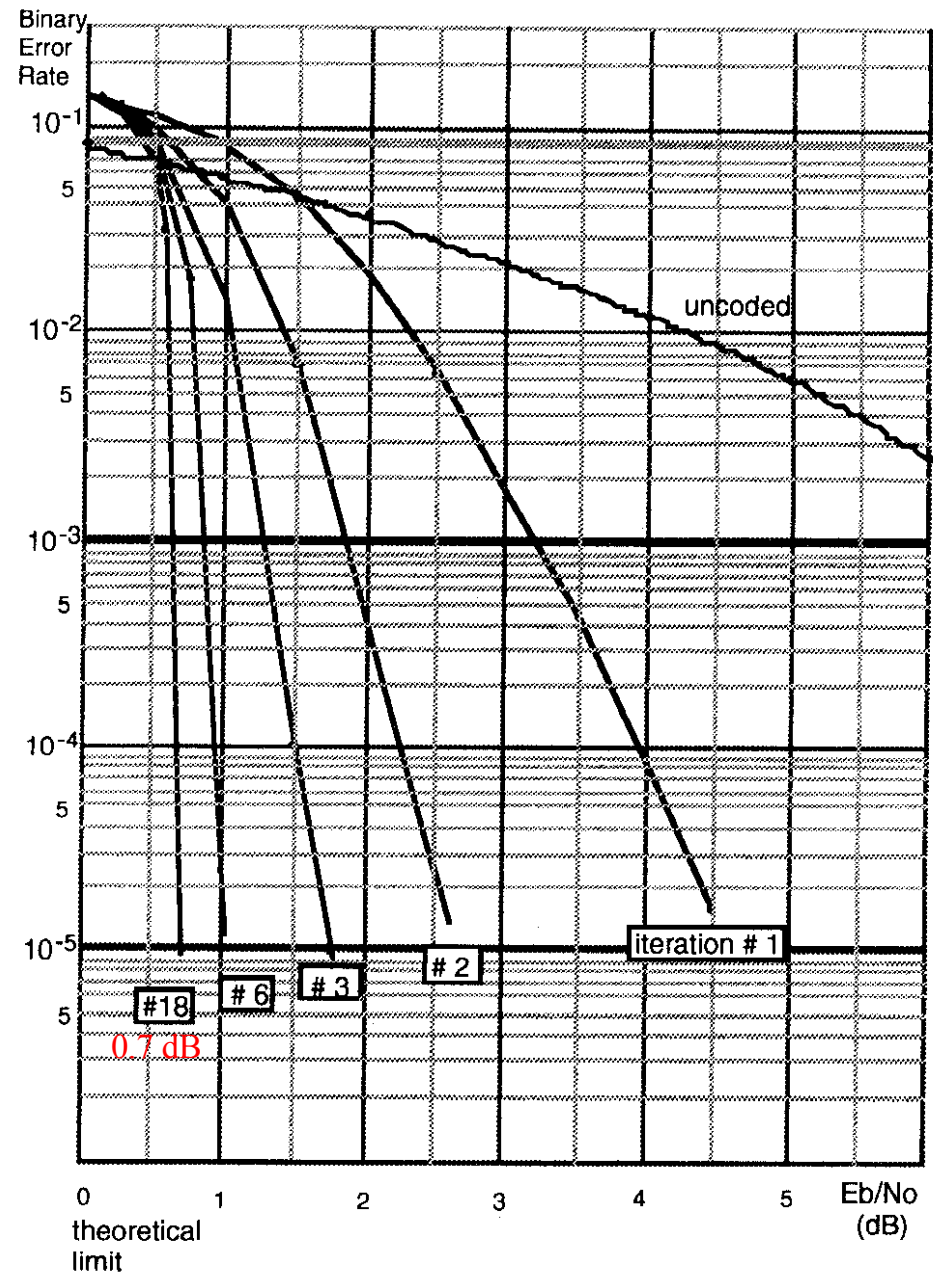
$$[r_1 \ r_2 \ r_3 \ r_5] = [x_1 \ x_2 \ x_3 \ x_5] + [w_1 \ w_2 \ w_3 \ w_5]$$

Parity-check bits x_4 and x_6 are punctured.

Decoder decodes x_1 and x_2 based on $[r_1 \ r_2 \ r_3 \ 0 \ r_5 \ 0]$.

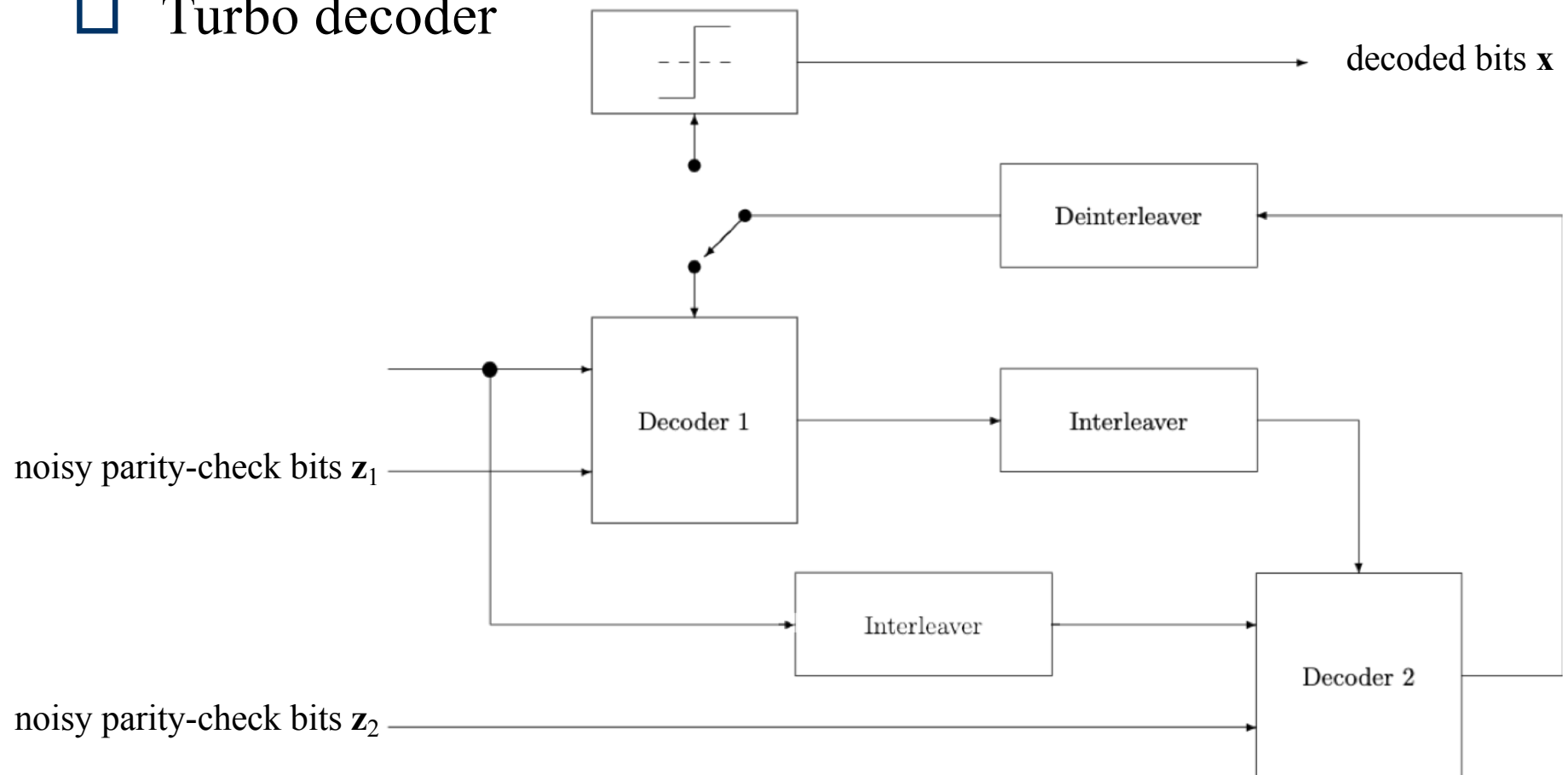
Turbo Codes

- Performance of Turbo codes
 - BER given by turbo coding with generators (37, 21) with punctuation and memory $m=4$, Berrou-Glavieux interleaver with size 256×256 and iterative MAP decoder (See Fig. 5 in the ICC'93 paper by Berrou *et. al*).
 - See Slide IDC6-77 for the Shannon limit **0.186 dB** for (2,1) code over the binary-input AWGN channels.



Turbo Codes

□ Turbo decoder

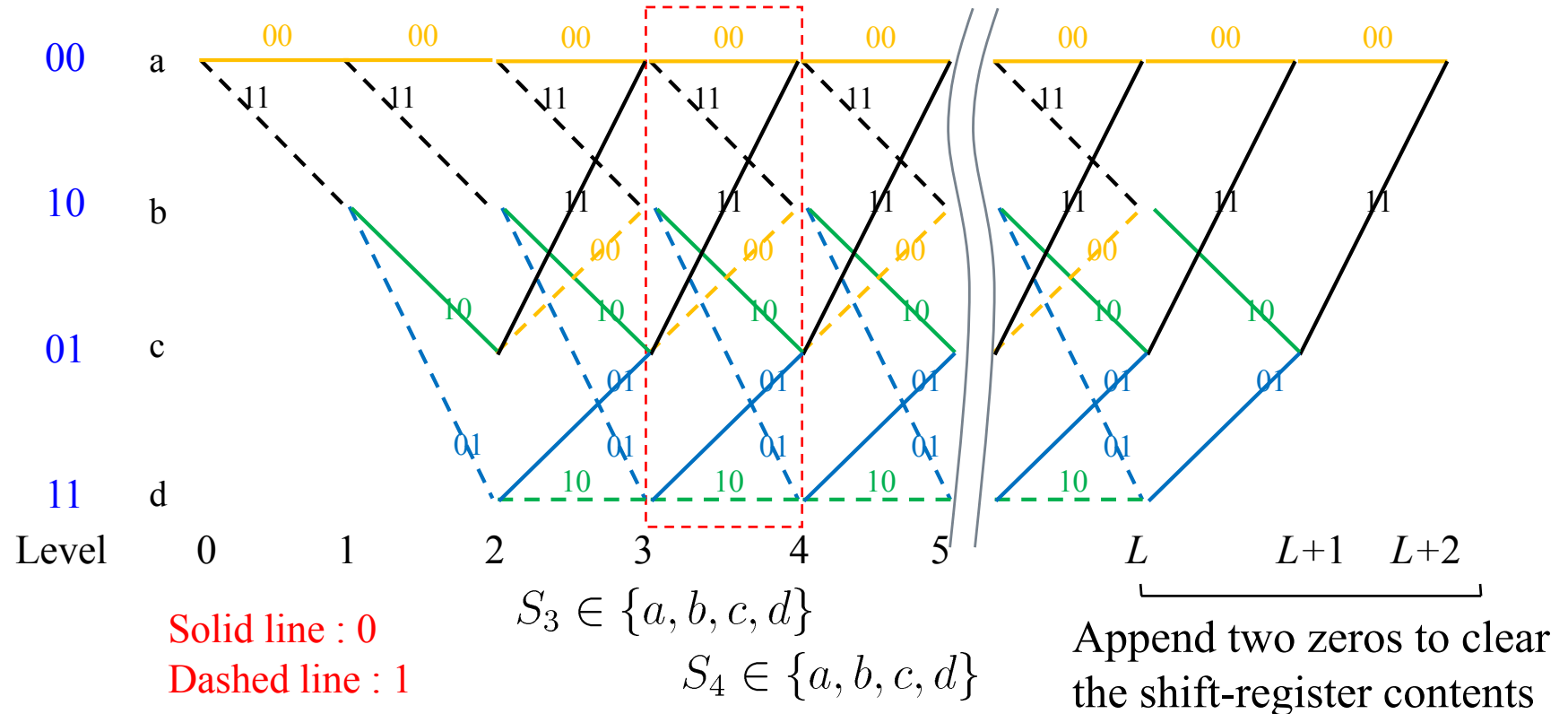


□ Turbo component decoder (BCJR algorithm or log-MAP algorithm)

■ Use to decode a code whose present state and present output are a function of the past state and current input bit.

Set of transitions corresponding to symbol 0 : $\mathcal{B}_{3,4}(0) = \{(a, a), (b, c), (c, a), (d, c)\}$

Set of transitions corresponding to symbol 1 : $\mathcal{B}_{3,4}(1) = \{(a, b), (b, d), (c, b), (d, d)\}$



- It minimizes the **bit error** directly rather than **word error**.

$$P(m_4 = 0|\mathbf{r}) = P((S_3, S_4) \in \mathcal{B}_{3,4}(0)|\mathbf{r})$$

Left-hand side = The probability of the 4th message bit = 0, given that the receiver receives \mathbf{r} .

Right-hand side = The probability of the encoder going through state S_3 and state S_4 in $\mathcal{B}_{3,4}(0)$, given that the receiver receives \mathbf{r} .

$$\begin{aligned}\Rightarrow l(4) &= \log \frac{\sum_{(S_3, S_4) \in \mathcal{B}_{3,4}(1)} P(S_3, S_4|\mathbf{r})}{\sum_{(S_3, S_4) \in \mathcal{B}_{3,4}(0)} P(S_3, S_4|\mathbf{r})} \\ &= \log \frac{\sum_{(S_3, S_4) \in \mathcal{B}_{3,4}(1)} P(S_3, S_4, \mathbf{r})}{\sum_{(S_3, S_4) \in \mathcal{B}_{3,4}(0)} P(S_3, S_4, \mathbf{r})}\end{aligned}$$

My derivation is based on the original work and is different from the textbook.

$$\begin{aligned}
P(S_3, S_4, \mathbf{r}) &= P(S_3, S_4, r_1^6, r_7^8, r_9^N) \\
&= P(r_9^N | S_3, S_4, r_1^6, r_7^8) P(S_3, S_4, r_1^6, r_7^8) \\
&= \underbrace{P(r_9^N | S_4)}_{\beta(S_4)} P(S_3, S_4, r_1^6, r_7^8)
\end{aligned}$$

$(S_3, r_1^6, r_7^8) \rightarrow S_4 \rightarrow r_9^N$
 forms a Markov chain.

$$\begin{aligned}
P(S_3, S_4, r_1^6, r_7^8) &= P(S_3, r_1^6) P(S_4, r_7^8 | S_3, r_1^6) \\
&= \underbrace{P(S_3, r_1^6)}_{\alpha(S_3)} \underbrace{P(S_4, r_7^8 | S_3)}_{\gamma(S_3, S_4)}
\end{aligned}$$

In the notations of α (past), β (future) and γ (now), we ignore the received vector \mathbf{r} .

$$\Rightarrow l(4) = \log \frac{\sum_{(S_3, S_4) \in \mathcal{B}_{3,4}(1)} \alpha(S_3) \beta(S_4) \gamma(S_3, S_4)}{\sum_{(S_3, S_4) \in \mathcal{B}_{3,4}(0)} \alpha(S_3) \beta(S_4) \gamma(S_3, S_4)}$$

$$\begin{aligned}
\alpha(S_3) &= P(S_3, r_1^6) \\
&= \sum_{S_2 \in \{a,b,c,d\}} P(S_2, S_3, r_1^4, r_5^6) \\
&= \sum_{S_2 \in \{a,b,c,d\}} P(S_2, r_1^4) P(S_3, r_5^6 | S_2, r_1^4) \\
&= \sum_{S_2 \in \{a,b,c,d\}} P(S_2, r_1^4) P(S_3, r_5^6 | S_2) \\
&= \sum_{S_2 \in \{a,b,c,d\}} \alpha(S_2) \gamma(S_2, S_3)
\end{aligned}$$

$$\text{Initial value } \alpha(S_0) = P(S_0, r_1^0) = P(S_0) = \begin{cases} 1, & S_0 = a; \\ 0, & S_0 = b; \\ 0, & S_0 = c; \\ 0, & S_0 = d \end{cases}$$

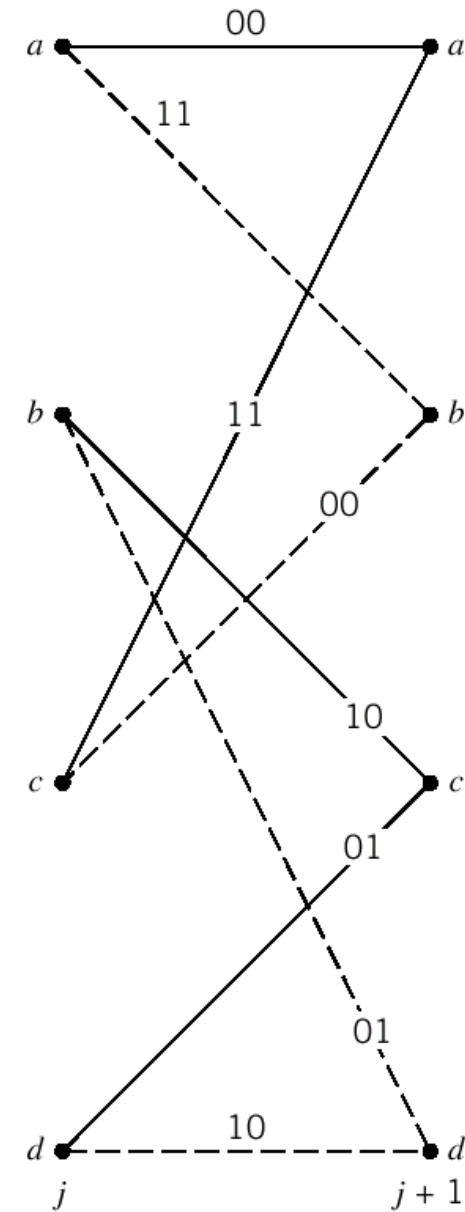
$$\text{Initial value } \beta(S_{L+m}) = \begin{cases} 1, & S_{L+m} = a; \\ 0, & S_{L+m} = b; \\ 0, & S_{L+m} = c; \\ 0, & S_{L+m} = d \end{cases}$$

$$\begin{aligned} \beta(S_4) &= P(r_9^N | S_4) \\ &= \sum_{S_5 \in \{a,b,c,d\}} P(S_5, r_9^{10}, r_{11}^N | S_4) \\ &= \sum_{S_5 \in \{a,b,c,d\}} P(r_{11}^N | S_4, S_5, r_9^{10}) P(S_5, r_9^{10} | S_4) \\ &= \sum_{S_5 \in \{a,b,c,d\}} P(r_{11}^N | S_5) P(S_5, r_9^{10} | S_4) \\ &= \sum_{S_5 \in \{a,b,c,d\}} \beta(S_5) \gamma(S_4, S_5) \end{aligned}$$

Note that the turbo codes use **systematic** code; hence, one of the code bit should be the same as the message bit

$$\begin{aligned} \gamma(S_3, S_4) &= P(S_4, r_7^8 | S_3) \\ &= P(r_7^8 | S_3, S_4) P(S_4 | S_3) \\ &= \underbrace{P(r_7^8 | x_7^8(S_3, S_4))}_{\text{channel}} \underbrace{P(S_4 | S_3)}_{\text{prior}} = \underbrace{P(r_7^8 | m_4, x_8(S_3, S_4))}_{\text{channel}} \underbrace{P(S_4 | S_3)}_{\text{prior}} \\ &= \underbrace{P(r_7 | m_4)}_{\text{systematic}} \underbrace{P(r_8 | x_8(S_3, S_4))}_{\text{parity}} \underbrace{P(S_4 | S_3)}_{\text{prior}} \end{aligned}$$

$$P(S_4|S_3) = \left\{ \begin{array}{ll} P(a|a) & = P(m_4 = 0) \\ P(b|a) & = P(m_4 = 1) \\ P(c|a) & = 0 \\ P(d|a) & = 0 \\ P(a|b) & = 0 \\ P(b|b) & = 0 \\ P(c|b) & = P(m_4 = 0) \\ P(d|b) & = P(m_4 = 1) \\ P(a|c) & = P(m_4 = 0) \\ P(b|c) & = P(m_4 = 1) \\ P(c|c) & = 0 \\ P(d|c) & = 0 \\ P(a|d) & = 0 \\ P(b|d) & = 0 \\ P(c|d) & = P(m_4 = 0) \\ P(d|d) & = P(m_4 = 1) \end{array} \right.$$



$$\text{Let } \tilde{\gamma}(S_3, S_4) = \underbrace{P(r_8|x_8(S_3, S_4))}_{\text{parity}}$$

$$\begin{aligned} \Rightarrow l(4) &= \log \frac{\sum_{(S_3, S_4) \in \mathcal{B}_{3,4}(1)} \alpha(S_3) \beta(S_4) \tilde{\gamma}(S_3, S_4) P(S_4|S_3) P(r_7|m_4)}{\sum_{(S_3, S_4) \in \mathcal{B}_{3,4}(0)} \alpha(S_3) \beta(S_4) \tilde{\gamma}(S_3, S_4) P(S_4|S_3) P(r_7|m_4)} \\ &= \log \frac{\sum_{(S_3, S_4) \in \mathcal{B}_{3,4}(1)} \alpha(S_3) \beta(S_4) \tilde{\gamma}(S_3, S_4) P(m_4 = 1) P(r_7|1)}{\sum_{(S_3, S_4) \in \mathcal{B}_{3,4}(0)} \alpha(S_3) \beta(S_4) \tilde{\gamma}(S_3, S_4) P(m_4 = 0) P(r_7|0)} \\ &= \underbrace{\log \frac{P(m_4 = 1)}{P(m_4 = 0)}}_{\substack{a \text{ priori } l_{\text{in}} \\ \text{(intrinsic)}}} + \underbrace{\log \frac{P(r_7|1)}{P(r_7|0)}}_{\text{systematic}} + \underbrace{\log \frac{\sum_{(S_3, S_4) \in \mathcal{B}_{3,4}(1)} \alpha(S_3) \beta(S_4) \tilde{\gamma}(S_3, S_4)}{\sum_{(S_3, S_4) \in \mathcal{B}_{3,4}(0)} \alpha(S_3) \beta(S_4) \tilde{\gamma}(S_3, S_4)}}_{\text{extrinsic } l_{\text{ex}}} \end{aligned}$$

Step 1: With $l_{\text{in}}(m_j)$ known, we can compute

$P(m_j = 0) = \frac{1}{1 + \exp\{l_{\text{in}}(m_j)\}}$ and $P(m_j = 1) = \frac{\exp\{l_{\text{in}}(m_j)\}}{1 + \exp\{l_{\text{in}}(m_j)\}}$
for each $1 \leq j \leq L$. We can in turn compute $\gamma(S_j, S_{j+1})$
for all $(S_j, S_{j+1}) \in \{a, b, c, d\}^2$ and for each $0 \leq j \leq j + m$.

Step 2: With γ available, we can recursively compute α and β
in the forward and backward fashions, respectively.

Step 3: With α , β and γ ready, we can compute

$$l(j) = \log \frac{P(m_j = 1|\mathbf{r})}{P(m_j = 0|\mathbf{r})} = \log \frac{\sum_{(S_{j-1}, S_j) \in \mathcal{B}_{j-1,j}(1)} \alpha(S_{j-1})\beta(S_j)\gamma(S_{j-1}, S_j)}{\sum_{(S_{j-1}, S_j) \in \mathcal{B}_{j-1,j}(0)} \alpha(S_{j-1})\beta(S_j)\gamma(S_{j-1}, S_j)}$$

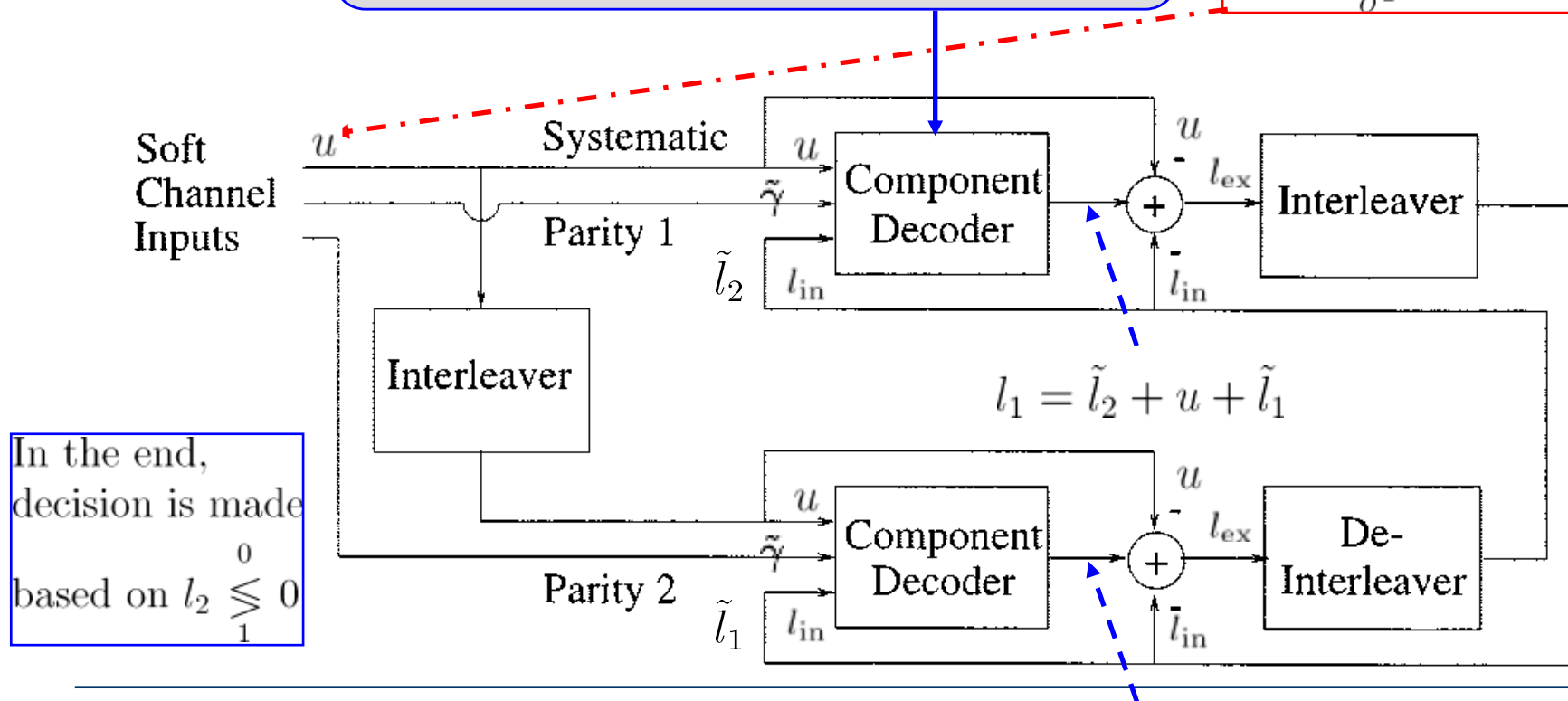
Step 4: Calculate $l_{\text{ex}}(j) = l(j) - \log \frac{P(r_{2j-1}|1)}{P(r_{2j-1}|0)} - l_{\text{in}}(j)$.

Observe $l(j) = l_{\text{in}}(j) + \log \frac{P(r_{2j-1}|1)}{P(r_{2j-1}|0)} + l_{\text{ex}}(j).$

Intuition: Recursion between these two

(Slide IDC 8-33) Compute γ based on $u, \tilde{\gamma}, l_{\text{in}}$
 (Slides IDC 8-32&33) Compute recursively α, β
 (Slides IDC 8-36) Compute l (Step 3)

$$\begin{aligned} u_j &= \log \frac{P(r_{2j-1}|1)}{P(r_{2j-1}|0)} \\ &= \log \frac{\exp \left\{ -\frac{(r_{2j-1} - (+1))^2}{2\sigma^2} \right\}}{\exp \left\{ -\frac{(r_{2j-1} - (-1))^2}{2\sigma^2} \right\}} \\ &= \frac{2}{\sigma^2} r_{2j-1} \end{aligned}$$



In the end,
 decision is made
 based on $l_2 \begin{matrix} 0 \\ \lessgtr \\ 1 \end{matrix}$

□ Turbo coding, although quite impressive in performance, is designed based on an empirical intuition.

■ For example, Berrou and Glaviexu wrote in their 1996 T-COM paper that

□ ... for very low SNRs, the BER can sometimes increase during the iterative decoding process. In order to overcome this effect, the extrinsic information \tilde{l}_1 (resp. \tilde{l}_2) has been divided by $(1+\theta|\tilde{l}_1|)$ (resp. $(1+\theta|\tilde{l}_2|)$). θ acts as a stability factor and its value of 0.15 was adopted after several simulation tests at $E_b/N_0 = 0.7$ dB.... [1, pp. 1270]

[1] Claude Berrou and Alain Glavieux, "Near optimal error correcting coding and decoding: Turbo-codes," *IEEE Trans. Comm.*, vol. 44, no. 10, pp. 1261-1271, Oct. 1996.

Low-Density Parity-Check (LDPC) Codes

- LDPC codes (also known as Gallager codes) are also iteratively decodable.
- Its advantages over turbo coding technique are
 - absence of low-weight codewords;
 - With a careless interleaver design, a turbo code may have low weight codewords, which is the main cause for error floor.
 - And iterative decoding with a lower complexity.

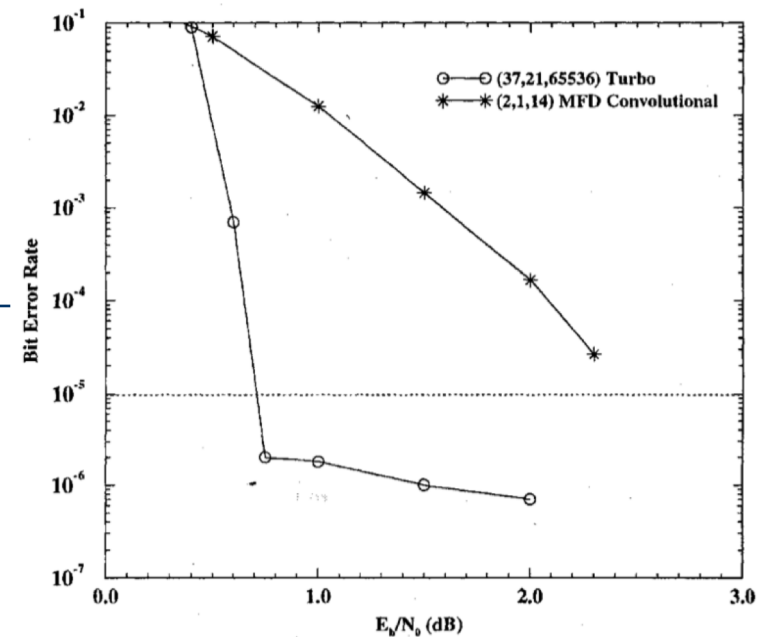
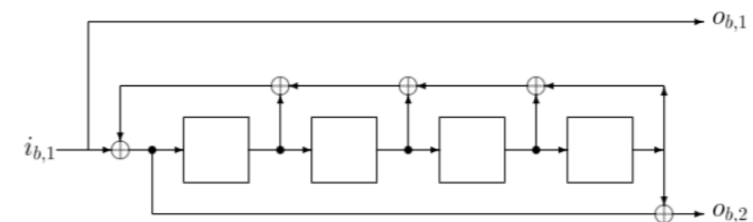


Fig. 1. Simulation results for a (37, 21, 65536) Turbo code and a (2, 1, 14) MFD convolutional code.

L. C. Perez, J. Seghers and D. J. Costello, "A Distance Spectrum Interpretation of Turbo Codes," *IEEE Trans. Info. Theory*, pp. 1698-1709, Nov. 1996.



$$\begin{aligned}
 G(D) &= \left[1 \frac{D^4 + 1}{D^4 + D^3 + D^2 + D + 1} \right] \\
 &= \left[1 \frac{(10, 001)_2}{(11, 111)_2} \right] \\
 &= \left[1 \frac{(2, 1)_8}{(3, 7)_8} \right]
 \end{aligned}$$

Low-Density Parity-Check Codes

- In notation, a regular LDPC code (with parity-check matrix $\mathbf{H}_{(n-k) \times n}$) is usually denoted by three tuple (n, t_c, t_r) .
 - n = block length
 - t_c = number of 1s in each column of n bits
 - t_r = number of 1s in each row of $(n-k)$ bits with $t_r > t_c$
 - It is not necessary to specify k since

$$(\# \text{ of 1s}) = nt_c = (n - k)t_r \Rightarrow \frac{t_c}{t_r} = 1 - \frac{k}{n}$$

□ Example: $(n, t_c, t_r) = (10, 3, 5)$.

$$\begin{bmatrix} 1 & 1 & 0 & 1 & 0 & 1 & 0 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 & 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 & 1 & 1 & 0 & 0 & 1 & 1 \\ 0 & 1 & 1 & 1 & 0 & 1 & 1 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 1 & 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 & 0 & 0 & 1 & 1 & 1 & 1 \end{bmatrix}_{(10-4) \times 10}$$

$$\frac{k}{n} = 1 - \frac{t_c}{t_r} = 1 - \frac{3}{5} = \frac{2}{5}$$

Low-Density Parity-Check Codes

- How to find the generator matrix for a given parity-check matrix for systematic LDPC codes?

$$\mathbf{c} = [\mathbf{b} : \mathbf{m}]$$

where $\begin{cases} \mathbf{b} \text{ are parity-check bits} \\ \mathbf{m} \text{ are message bits} \end{cases}$

$$\mathbf{H}_{n \times (n-k)}^T = \begin{bmatrix} \mathbf{H}_1 \\ \cdots \\ \mathbf{H}_2 \end{bmatrix} \Rightarrow [\mathbf{b} : \mathbf{m}] \begin{bmatrix} \mathbf{H}_1 \\ \cdots \\ \mathbf{H}_2 \end{bmatrix} \Rightarrow \mathbf{b}\mathbf{H}_1 + \mathbf{m}\mathbf{H}_2 = \mathbf{0}$$

The generator matrix of a systematic code (including LDPC codes) must be of the shape

$$\mathbf{G}_{k \times n} = \begin{bmatrix} \mathbf{P}_{k \times (n-k)} & \vdots & \mathbf{I}_k \end{bmatrix} \Rightarrow \mathbf{m}_{1 \times k} \mathbf{P}_{k \times (n-k)} = \mathbf{b}_{1 \times (n-k)}$$

This concludes to:

$$\mathbf{m}\mathbf{P}\mathbf{H}_1 + \mathbf{m}\mathbf{H}_2 = \mathbf{0} \Rightarrow \mathbf{P} = \mathbf{H}_2\mathbf{H}_1^{-1} \Rightarrow \mathbf{G} = \begin{bmatrix} \mathbf{H}_2\mathbf{H}_1^{-1} & \vdots & \mathbf{I}_k \end{bmatrix}$$

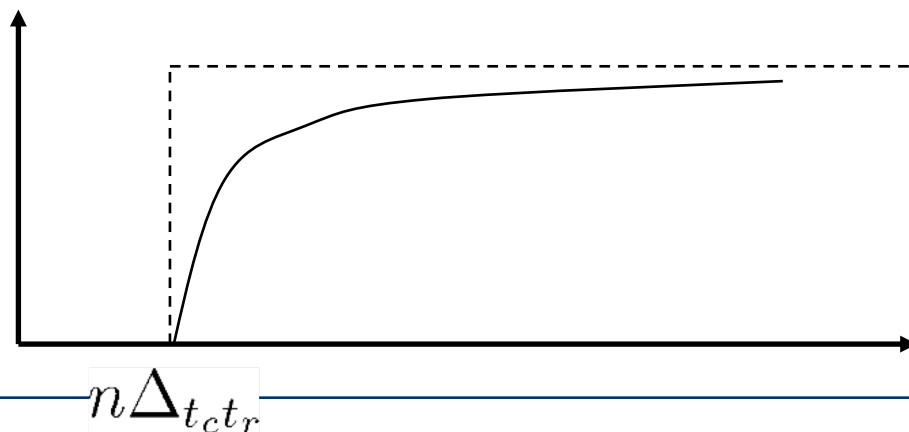
Low-Density Parity-Check Codes

□ Remarks

- Low-density parity-check code gets its name since the number of 1s in each row and column is small (**low-density**).
- If the number of 1s in each row and also in each column is fixed, the LDPC code is said to be *regular*.
- Under regularity, the inverse matrix of \mathbf{H}_1 may be difficult to make to exist.
- Hence, some “manipulation” or even allowing some “irregularity” is sometimes necessary.

Low-Density Parity-Check Codes

- Minimum distance of LDPC codes
 - By uniformly selecting codeword pairs, the pairwise distance becomes a random variable, for which the cumulative distribution function (cdf) can be empirically plotted.
 - It is shown that this cdf can be overbounded by a unit step function as shown below.



Low-Density Parity-Check Codes

t_c	t_r	Code rate k/n	$\Delta_{t_c t_r}$
5	6	0.167	0.255
4	5	0.2	0.210
3	4	0.25	0.122
4	6	0.333	0.129
3	5	0.4	0.044
3	6	0.5	0.023

$$(\# \text{ of 1s}) = nt_c = (n - k)t_r \Rightarrow \frac{t_c}{t_r} = 1 - \frac{k}{n}$$

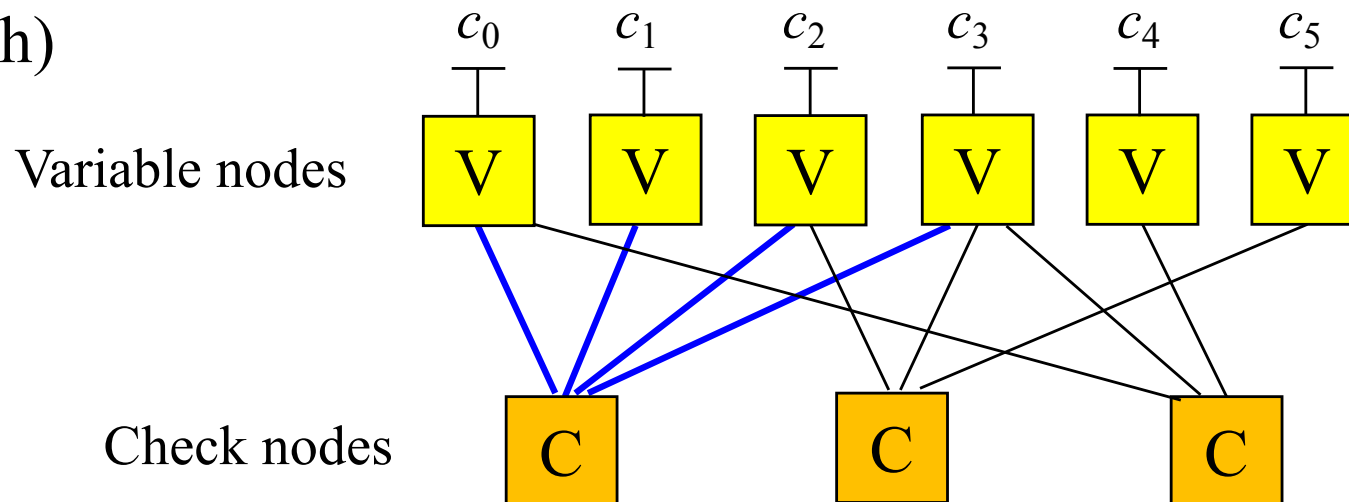
Low-density parity-check codes

- Probabilistic decoding of LDPC codes (Mackay and Neal, 1996)
 - In the form of belief propagation or message passing.
 - Forney's factor graph (Bipartite graph)

Have $(n - k) = (6 - 3)$
parity-check equations

$$[c_0, c_1, \dots, c_5] \begin{bmatrix} 1 & 0 & 1 \\ 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}_{6 \times 3} = \mathbf{0}_{1 \times 3}$$

Need to solve 6 variables
 $[c_0, c_1, \dots, c_5]$



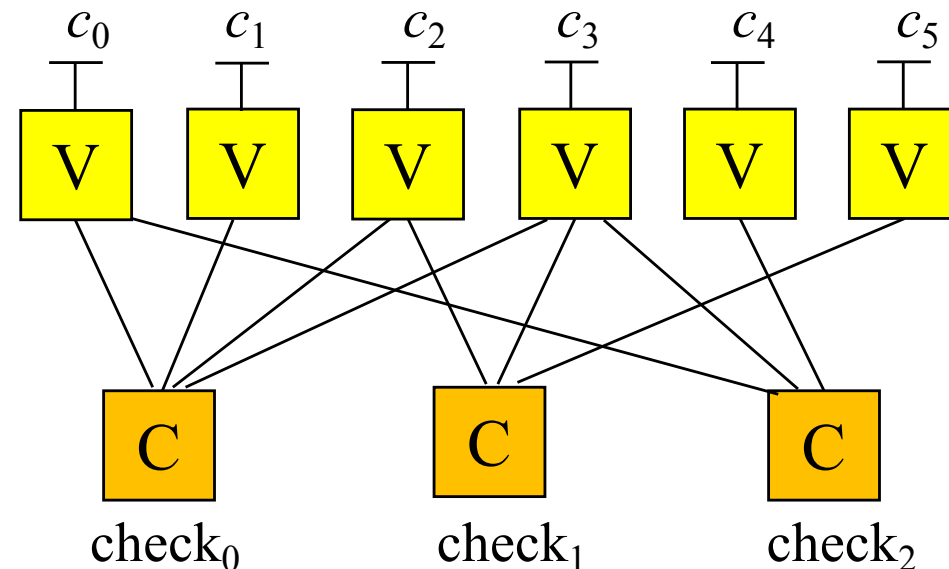
Map $\{0, 1\}$ to $\{1, -1\}$ and thus change “xor” to “product”.

Abuse the notation by retaining c_j to be the information in $\{1, -1\}$.

Hence, for each check node, we should have even number of -1 .

In other words,

$$\begin{cases} \text{Check}_0 = c_0 c_1 c_2 c_3 = 1; \\ \text{Check}_1 = c_2 c_3 c_5 = 1; \\ \text{Check}_2 = c_0 c_3 c_4 = 1; \end{cases}$$



$\text{Bit}(0) = \{0, 2\}$, $\text{Bit}(1) = \{0\}$, $\text{Bit}(2) = \{0, 1\}$, $\text{Bit}(3) = \{0, 1, 2\}$, $\text{Bit}(4) = \{2\}$, $\text{Bit}(5) = \{1\}$

$\text{Check}(0) = \{0, 1, 2, 3\}$, $\text{Check}(1) = \{2, 3, 5\}$, $\text{Check}(2) = \{0, 3, 4\}$

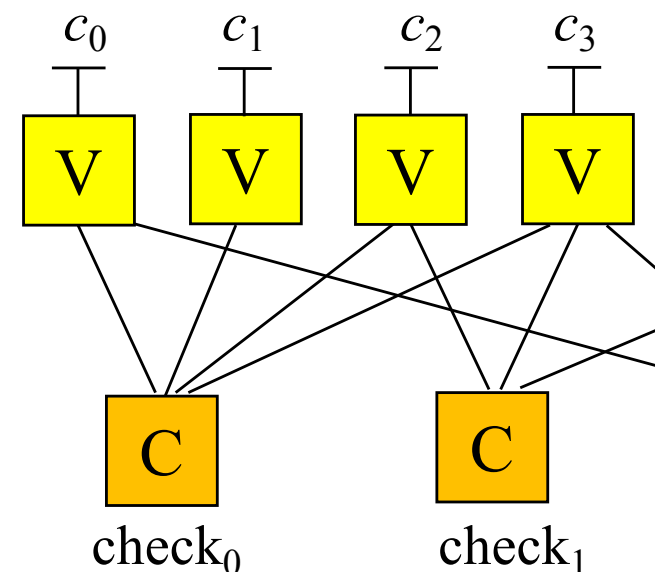
$Q_{i,j}^x$ = probability that $\text{Check}_i = 1$, with $c_j = x$ and the messages that it receives from the variable nodes connected to it.

$$\Rightarrow E[c_1 c_2 c_3] = 1 \times Q_{0,0}^1 + (-1) \times Q_{0,0}^{-1} = Q_{0,0}^1 - Q_{0,0}^{-1}$$

$P_{i,j}^x$ = probability that $c_j = x$, given that the information derived via all checks connected to c_j except Check_i .

$$\begin{aligned} \Rightarrow E[c_1 c_2 c_3] &= E[c_1] E[c_2] E[c_3] \quad (\text{Assume independence among } \{c_j\}.) \\ &= (P_{0,1}^1 - P_{0,1}^{-1})(P_{0,2}^1 - P_{0,2}^{-1})(P_{0,3}^1 - P_{0,3}^{-1}) \end{aligned}$$

$$\begin{cases} Q_{0,0}^1 - Q_{0,0}^{-1} = \prod_{j \in \text{Check}(0) \setminus \{0\}} (P_{0,j}^1 - P_{0,j}^{-1}) \\ Q_{0,0}^1 + Q_{0,0}^{-1} = 1 \end{cases} \Rightarrow \begin{cases} Q_{0,0}^1 = \frac{1}{2} \left(1 + \prod_{j \in \text{Check}(0) \setminus \{0\}} (P_{0,j}^1 - P_{0,j}^{-1}) \right) \\ Q_{0,0}^{-1} = \frac{1}{2} \left(1 - \prod_{j \in \text{Check}(0) \setminus \{0\}} (P_{0,j}^1 - P_{0,j}^{-1}) \right) \end{cases}$$



- This summarizes to the so-called **Horizontal step**:

$$\text{Horizontal step: Update } Q_{i,j}^1 = \frac{1}{2} \left(1 + \prod_{k \in \text{Check}(i) \setminus \{j\}} (2P_{i,k}^1 - 1) \right)$$

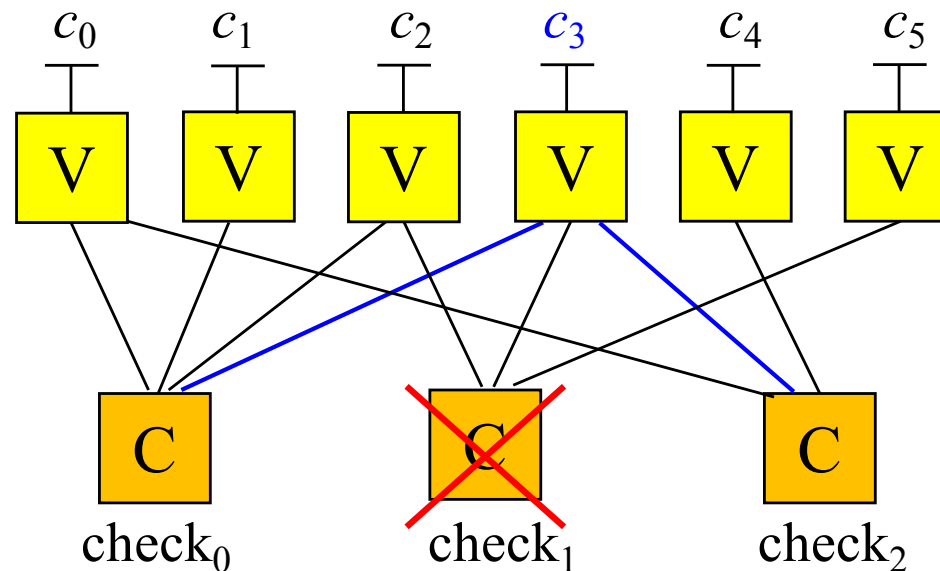
$$\begin{bmatrix} P_{0,0}^1 & P_{1,0}^1 & P_{2,0}^1 \\ P_{0,1}^1 & P_{1,1}^1 & P_{2,1}^1 \\ P_{0,2}^1 & P_{1,2}^1 & P_{2,2}^1 \\ P_{0,3}^1 & P_{1,3}^1 & P_{2,3}^1 \\ P_{0,4}^1 & P_{1,4}^1 & P_{2,4}^1 \\ P_{0,5}^1 & P_{1,5}^1 & P_{2,5}^1 \end{bmatrix} \Rightarrow \begin{bmatrix} Q_{0,0}^1 & Q_{1,0}^1 & Q_{2,0}^1 \\ Q_{0,1}^1 & Q_{1,1}^1 & Q_{2,1}^1 \\ Q_{0,2}^1 & Q_{1,2}^1 & Q_{2,2}^1 \\ Q_{0,3}^1 & Q_{1,3}^1 & Q_{2,3}^1 \\ Q_{0,4}^1 & Q_{1,4}^1 & Q_{2,4}^1 \\ Q_{0,5}^1 & Q_{1,5}^1 & Q_{2,5}^1 \end{bmatrix}$$

□ Next we move on to the **Vertical step**:

$Q_{i,j}^x$ = probability that $\text{Check}_i = 1$, with $c_j = x$ and the messages that it receives from the variable nodes connected to it.

$P_{i,j}^x$ = probability that $c_j = x$, given that the information derived via all checks connected to c_j except Check_i .

$P_{1,3}^1$ should be proportional to $p_3^1 Q_{0,3}^1 Q_{2,3}^1$,
 and $P_{1,3}^{-1}$ should be proportional to $p_3^{-1} Q_{0,3}^{-1} Q_{2,3}^{-1}$,
 where p_j^1 and p_j^{-1} are the initial probabilities of $c_j = 1$
 and $c_j = -1$, respectively.



Vertical step: Update

$$P_{i,j}^1 = \frac{p_j^1 \prod_{k \in \text{Bit}(j) \setminus \{i\}} Q_{k,j}^1}{p_j^1 \prod_{k \in \text{Bit}(j) \setminus \{i\}} Q_{k,j}^1 + (1 - p_j^1) \prod_{k \in \text{Bit}(j) \setminus \{i\}} (1 - Q_{k,j}^1)}$$

$$\begin{bmatrix} Q_{0,0}^1 & Q_{1,0}^1 & Q_{2,0}^1 \\ Q_{0,1}^1 & Q_{1,1}^1 & Q_{2,1}^1 \\ Q_{0,2}^1 & Q_{1,2}^1 & Q_{2,2}^1 \\ Q_{0,3}^1 & Q_{1,3}^1 & Q_{2,3}^1 \\ Q_{0,4}^1 & Q_{1,4}^1 & Q_{2,4}^1 \\ Q_{0,5}^1 & Q_{1,5}^1 & Q_{2,5}^1 \end{bmatrix} \Rightarrow \begin{bmatrix} P_{0,0}^1 & P_{1,0}^1 & P_{2,0}^1 \\ P_{0,1}^1 & P_{1,1}^1 & P_{2,1}^1 \\ P_{0,2}^1 & P_{1,2}^1 & P_{2,2}^1 \\ P_{0,3}^1 & P_{1,3}^1 & P_{2,3}^1 \\ P_{0,4}^1 & P_{1,4}^1 & P_{2,4}^1 \\ P_{0,5}^1 & P_{1,5}^1 & P_{2,5}^1 \end{bmatrix}$$

$$P_j^1 = \frac{p_j^1 \prod_{k \in \text{Bit}(j)} Q_{k,j}^1}{p_j^1 \prod_{k \in \text{Bit}(j)} Q_{k,j}^1 + (1 - p_j^1) \prod_{k \in \text{Bit}(j)} (1 - Q_{k,j}^1)} \quad \text{and} \quad p_j^1 = P_j^1$$

Initialization:

$$P_{i,j}^1 = p_j^1$$

Horizontal step:

$$Q_{i,j}^1 = \frac{1}{2} \left(1 + \prod_{k \in \text{Check}(i) \setminus \{j\}} (2P_{i,k}^1 - 1) \right)$$

Vertical step:

$$P_{i,j}^1 = \frac{p_j^1 \prod_{k \in \text{Bit}(j) \setminus \{i\}} Q_{k,j}^1}{p_j^1 \prod_{k \in \text{Bit}(j) \setminus \{i\}} Q_{k,j}^1 + (1 - p_j^1) \prod_{k \in \text{Bit}(j) \setminus \{i\}} (1 - Q_{k,j}^1)}$$

recursion



Decision step:

$$P_j^1 = \frac{p_j^1 \prod_{k \in \text{Bit}(j)} Q_{k,j}^1}{(1 - p_j^1) \prod_{k \in \text{Bit}(j)} (1 - Q_{k,j}^1) + p_j^1 \prod_{k \in \text{Bit}(j)} Q_{k,j}^1} \stackrel{1}{\underset{0}{\leq}} 1 - P_j^1$$

Termination:

If $\hat{\mathbf{c}}\mathbf{H}^T = \mathbf{0}$, the algorithm stops;
else $p_j^1 = P_j^1$ and go to Horizontal step.

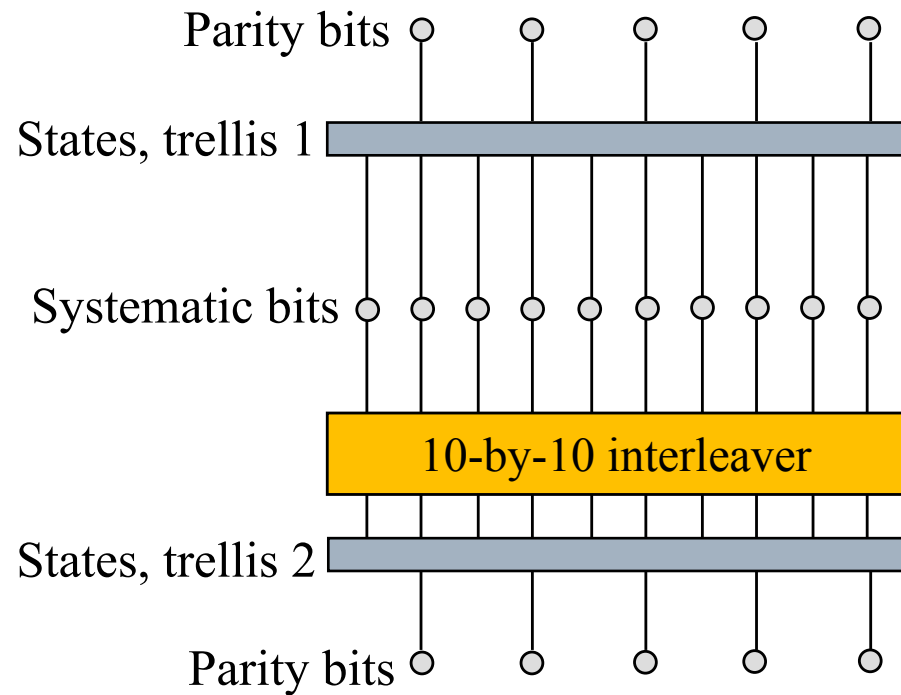
□ Final remark

- Regular LDPC codes do not appear to come as close to Shannon's limit as their turbo code counterparts.
- Hence, irregular LDPC codes are more popular.
 - The number of 1s in each column may vary.
 - The number of 1s in each row may vary.

Irregular LDPC Codes

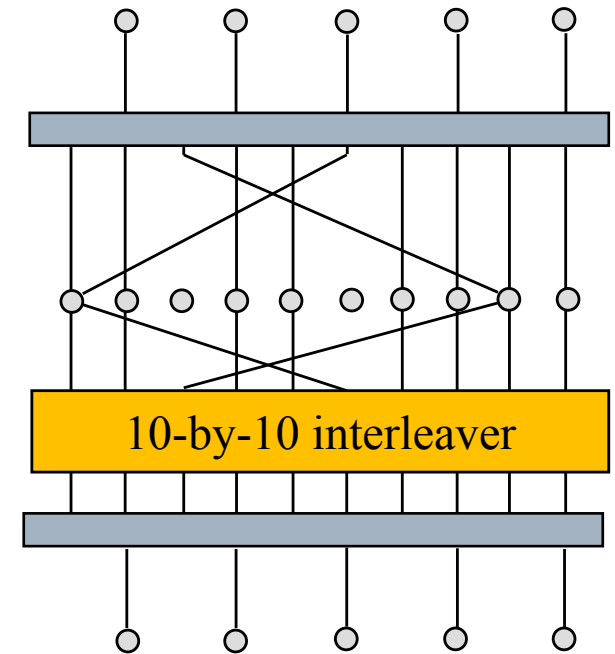
- The performance of turbo codes and LDPC codes can be further improved by “irregularity”.
 - By “irregularity”, we mean that each systematic bit is not used the same number of times.
 - For example, regular turbo code indicates that each systematic bit is used twice in the encoding process.

Regular (20, 10) turbo code



Punctured $\frac{1}{2}$
convolutional code

Irregular (18, 8) turbo code
(Bits 0 and 6 are used four times,
while bits 1, 2, 3, 4, 5, 7 are used
only twice.)



Irregular LDPC Codes

- Why irregularity gives better performance?
 - The codeword is “bit-wisely dependent”.

000000

000111

111000

111111

- If we give a much better estimation on certain positions, e.g., bit 0 and bit 4 in the above example, then the transmitted codeword may be more easily identified (via iterative decoding).

Irregular LDPC Codes

(See Figure 10.33 in textbook.)

(Code rate = $\frac{1}{2}$)

