Digital Communications Chapter 1. Introduction

Po-Ning Chen, Professor

Institute of Communications Engineering National Chiao-Tung University, Taiwan

What we study in this course is:

• Theories of information transmission in digital form from one or more sources to one or more destinations.

1.1 Elements of digital communication system

Functional diagram of a digital communication system

Basic elements of a digital communication system

Physical channel media

- (magnetic-electrical signaled) Wireline channel
	- **•** Telephone line, twisted-pair and coaxial cable, etc.
- (modulated light beam) Fiber-optical channel
- (antenna radiated) Wireless electromagnetic channel
	- **•** ground-wave propagation, sky-wave propagation, line-of-sight (LOS) propagation, etc.
- (multipath) Underwater acoustic channel
- ... etc.
- **Virtual channel**
	- Storage channel
		- Magnetic storage, CD, DVD, etc.

1.2 Comm channels and their characteristics

Channel impairments

- Thermal noise (additive noise)
- Signal attenuation
- Amplitude and phase distortion
- Multi-path distortion

Limitations of channel usage

- Transmission power
- Receiver sensitivity
- **•** Bandwidth
- **•** Transmission time

1.3 Math models for communication channels Additive noise channel (with attenuation)

In studying these channels, a mathematical model is necessary.

where

- \bullet α is the attenuation factor
- *s(t)* is the transmitted signal
- \bullet $n(t)$ is the additive random noise (a random process, usually Gaussian)

1.3 Math models for communication channels

Linear filter channel with additive noise

To meet the specified bandwidth limitation

$$
r(t) = s(t) \star c(t) + n(t)
$$

=
$$
\int_{-\infty}^{\infty} c(\tau) s(t - \tau) d\tau + n(t)
$$

1.3 Math models for communication channels Linear time-variant (LTV) filter channel with additive noise

$$
r(t) = s(t) \star c(\tau; t) + n(t)
$$

$$
= \int_{-\infty}^{\infty} c(\tau;t) s(t-\tau) d\tau + n(t)
$$

- \bullet τ is the argument for filtering.
- **•** *t* is the argument for time-dependence.
- The time-invariant filter can be viewed as a special case of the time-variant filter.

Assume $n(t) = 0$ (noise-free).

LTI versus LTV

1.3 Math models for communication channels LTV filter channel with additive noise

 $c(\tau; t)$ usually has the form

$$
c(\tau;t) = \sum_{k=1}^L a_k(t) \delta(\tau - \tau_k)
$$

where

- ${a_k(t)}_{k=1}^L$ represent the possibly time-varying attenuation factor for the *L* multipath propagation paths
- $\{\tau_k\}_{k=1}^L$ are the corresponding time delays.

Hence

$$
r(t) = \sum_{k=1}^{L} a_k(t) s(t - \tau_k) + n(t)
$$

1.3 Math models for communication channels Time varying multipath fading channel

 $r(t) = a_1(t)s(t-\tau_1) + a_2(t)s(t-\tau_2) + a_3(t)s(t-\tau_3) + n(t)$

- Morse code (1837)
	- Variable-length binary code for telegraph
- Baudot code (1875)
	- Fixed-length binary code of length 5
- Nyquist (1924)
	- Determine the maximum signaling rate without intersymbol interference over, e.g., a telegraph channel

- Nyquist (1924)
	- Define basic pulse shape $g(t)$ that is bandlimited to W.

 $g(t)$

 \bullet One wishes to transmit {-1, 1} signals in terms of $g(t)$, or equivalently, one wishes to transmit a_0 , a_1 , a_2 , ... in {−1, ¹} in terms of *s*(*t*) defined as

$$
s(t) = a_0 g(t) + a_1 g(t-T) + a_2 g(t-2T) + \cdots
$$

Example. $(a_0, a_1, a_2, \ldots) = (+1, -1, +1, \ldots).$

Digital Communications: Chapter 1 Ver. 2018*.*07*.*10 Po-Ning Chen 14 / 22

- Question that Nyquist shoots for:
	- What is the maximum rate that the data can be transmitted under the constraint that $g(t)$ causes no intersymbol interference (at the sampling instances)?

Answer : 2*W* pulses/second. (Not 2*W* bits/second!)

• What $g(t)$ can achieve this rate? Answer :

$$
g(t) = \frac{\sin(2\pi Wt)}{2\pi Wt}
$$

- Conclusion:
	- A bandlimited-to-*W* basic pulse shape signal (or symbol) can convey at most 2*W* pulses/second (or symbols/second) without introducing inter-pulse (or inter-symbol) interference.

1.4 A historical perspective in the developement of digital communications - Sampling theorem

- **•** Shannon (1948)
	- Sampling theorem
		- A signal of bandwidth *W* can be reconstructed from samples taken at the Nyquist rate (= 2*W* samples/second) using the interpolation formula

$$
s(t)=\sum_{n=-\infty}^{\infty} s\left(\frac{n}{2W}\right)\times\left(\frac{\sin[2\pi W(t-n/(2W))]}{2\pi W(t-n/(2W))}\right).
$$

1.4 A historical perspective in the developement of digital communications - Shannon's channel coding theorem

Channel capacity of additive white Gaussian noise

$$
C = W \log_2 \left(1 + \frac{P}{W N_0} \right) \quad \text{bits/second}
$$

where $\begin{cases} \end{cases}$ *W* is the bandwidth of the bandlimited channel, *P* is the average transmitted power, *N*⁰ is single-sided noise power per hertz.

- Shannon′ s channel coding theorem
	- Let *R* be the information rate of the source. Then
		- \bullet if $R < C$, it is theoretically possible to achieve reliable (asymptotically error-free) transmission by appropriate coding;
		- if $R > C$, reliable transmission is impossible.

This gives birth to a new field named Information Theory.

- Other important contributions
	- Harvey (1928), based on Nyquists result, concluded that
		- a maximum reliably transmitted data rate exists for a bandlimited channel under maximum transmitted signal amplitude constraint and minimum transmitted signal amplitude resolution constraint.
	- Kolmogorov (1939) and Wiener (1942)
		- Optimum linear (Kolmogorov-Wiener) filter whose output is the best mean-square approximation to the desired signal *s*(*t*) in presence of additive noise
	- Kotenikov (1947), Wozencraft and Jacobs (1965)
		- Use geometric approach to analyze various coherent digital communication systems.
	- \bullet Hamming (1950)
		- Hamming codes

Other important contributions (Continue)

- Muller (1954), Reed (1954), Reed and Solomon (1960), Bose and Ray-Chaudhuri (1960), and Goppa (1970,1971)
	- New block codes, such as Reed-Solomon codes, Bose-Chaudhuri-Hocquenghem (BCH) codes and Goppa codes.
- Forney (1966)
	- Concatenated codes
- Chien (1964), Berlekamp (1968)
	- Berlekamp-Massey BCH-code decoding algorithm

- Other important contributions (Continue)
	- Wozencraft and Reiffen (1961), Fano (1963), Zigangirov (1966), Jelinek (1969), Forney (1970, 1972, 1974) and Viterbi (1967, 1971)
		- Convolusional code and its decoding
	- Ungerboeck (1982), Forney *et al.* (1984), Wei (1987)
		- **•** Trellis-coded modulation
	- Ziv and Lempel (1977, 1978) and Linde *et al.* (1980)
		- Source encoding and decoding algorithms, such as Lempel-Ziv code
	- Berrou *et al.* (1993)
		- Turbo code and iterative decoding

- Other important contributions (Continue)
	- Gallager (1963), Davey and Mackay (1998)
		- Low-density parity-check (LDPC) code and the sum-product decoding algorithm

What you learn from Chapter 1

- Mathematical models of \bullet
	- **•** time-variant and time-invariant additive noise channels
	- multipath channels
- Nyquist rates and Sampling theorem