# 6. Special First-Order Ordinary Differential Equations

## **Linear Differential Equations**

A 1<sup>st</sup>-order ODE is said to be linear if it can be expressed by the following form

(6-1) 
$$y' + p(x)y = q(x)$$

where p(x) and q(x) are continuous on an interval I of x. The linearity can be seen from the terms on the left-hand side, which are defined as

$$(6-2) L[y] \equiv y' + p(x)y$$

It is easy to check that  $L[a_1y_1 + a_2y_2] = a_1L[y_1] + a_2L[y_2]$ , i.e., the operator (6-2) satisfies the superposition principle. Hence,  $L[y] \equiv y' + p(x)y$  is a linear operator and we call (6-1) a linear ODE.

To solve the 1<sup>st</sup>-order linear ODE (6-1), we can adopt the method of integrating factor by choosing  $\mu = e^{\int p(x)dx}$ . Then, multiply  $\mu = e^{\int p(x)dx}$  to (6-1) and obtain

(6-3) 
$$p(x)e^{\int p(x)dx}y - q(x)e^{\int p(x)dx} + e^{\int p(x)dx}y' = 0$$

where  $M = p(x)e^{\int p(x)dx}y - q(x)e^{\int p(x)dx}$  and  $N = e^{\int p(x)dx}$ . Since

(6-4) 
$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x} = p(x)e^{\int p(x)dx}$$

we know that (6-3) is exact and a potential function  $\varphi$  exists such that

$$\frac{\partial \varphi}{\partial x} = M$$
 and  $\frac{\partial \varphi}{\partial y} = N$ . Hence, from  $\frac{\partial \varphi}{\partial y} = N = e^{\int p(x)dx}$ , we have

(6-5) 
$$\varphi = e^{\int p(x)dx} y + g(x)$$

which leads to

(6-6) 
$$\frac{\partial \varphi}{\partial x} = p(x)e^{\int p(x)dx}y + g'(x)$$

Further from  $\frac{\partial \varphi}{\partial x} = M = p(x)e^{\int p(x)dx}y - q(x)e^{\int p(x)dx}$ , we obtain

(6-7) 
$$g'(x) = -q(x)e^{\int p(x)dx}$$

Let

(6-8) 
$$g(x) = -\int q(x)e^{\int p(x)dx}dx$$

then the potential function is

(6-9) 
$$\varphi = e^{\int p(x)dx} y - \int q(x)e^{\int p(x)dx} dx$$

and the solution is

(6-10) 
$$e^{\int p(x)dx} y - \int q(x)e^{\int p(x)dx} dx = C$$

or explicitly expressed as

(6-11) 
$$y = e^{-\int p(x)dx} \int q(x)e^{\int p(x)dx} dx + Ce^{-\int p(x)dx}$$

with C constant. This is also the explicit solution of y' + p(x)y = q(x) because the integrating factor  $\mu = e^{\int p(x)dx} \neq 0$ .

In fact, the 1<sup>st</sup>-order linear ODE (6-1) can be also solved from by multiplying the integrating factor  $e^{\int p(x)dx}$ , i.e.,

(6-12) 
$$e^{\int p(x)dx} y' + p(x)e^{\int p(x)dx} y = q(x)e^{\int p(x)dx}$$

Since 
$$\frac{d}{dx} \left( e^{\int p(x)dx} y \right) = e^{\int p(x)dx} y' + p(x) e^{\int p(x)dx} y$$
, we have

(6-13) 
$$\frac{d}{dx}\left(e^{\int p(x)dx}y\right) = q(x)e^{\int p(x)dx}$$

which leads to

(6-14) 
$$e^{\int p(x)dx}y = \int q(x)e^{\int p(x)dx}dx + C$$

with C constant. Clearly,

(6-15) 
$$y = e^{-\int p(x)dx} \int q(x)e^{\int p(x)dx} dx + Ce^{-\int p(x)dx}$$

same as the solution shown in (6-11).

The solution (6-15) is not unique since constant C is arbitrary. As mentioned before, C can be uniquely determined if the initial condition  $y(x_0) = y_0$  is given. Rewrite (6-15) as

(6-16) 
$$y(x) = e^{-\int_{x_0}^x p(\lambda)d\lambda} \int_{x_0}^x q(\tau) e^{\int_{x_0}^\tau p(\lambda)d\lambda} d\tau + Ce^{-\int_{x_0}^x p(\lambda)d\lambda}$$

and then,

(6-17) 
$$y(x_0) = e^{-\int_{x_0}^{x_0} p(\lambda)d\lambda} \int_{x_0}^{x_0} q(\tau) e^{\int_{x_0}^{\tau} p(\alpha)d\alpha} d\tau + Ce^{-\int_{x_0}^{x_0} p(\lambda)d\lambda} = C = y_0$$

In conclusion, for the following IVP

(6-18) 
$$y' + p(x)y = q(x), \quad y(x_0) = y_0$$

the solution can be uniquely determined as

(6-19) 
$$y(x) = e^{-\int_{x_0}^{x} p(\lambda)d\lambda} \int_{x_0}^{x} q(\tau) e^{\int_{x_0}^{\tau} p(\lambda)d\lambda} d\tau + y_0 e^{-\int_{x_0}^{x} p(\lambda)d\lambda}$$
$$= \int_{x_0}^{x} q(\tau) e^{-\int_{\tau}^{x} p(\lambda)d\lambda} d\tau + y_0 e^{-\int_{x_0}^{x} p(\lambda)d\lambda}$$

Next, let's take some examples of 1<sup>st</sup>-order ODE for demonstration.

Consider  $y' + 2y = \sin 3x$  with initial condition y(0)=1. Since p(x)=2, the integrating factor is given as

(6-20) 
$$\mu = e^{\int p(x)dx} = e^{2x}$$

Multiplying  $\mu = e^{2x}$  yields  $e^{2x}y' + 2e^{2x}y = e^{2x}\sin 3x$ , i.e.,

$$(6-21) \qquad \frac{d}{dx} \left( e^{2x} y \right) = e^{2x} \sin 3x$$

Hence,

(6-22) 
$$e^{2x}y = \int e^{2x}\sin 3x dx + C = \frac{2}{13}e^{2x}\sin 3x - \frac{3}{13}e^{2x}\cos 3x + C$$

i.e., the solution is

(6-23) 
$$y = \frac{1}{13} (2 \sin 3x - 3 \cos 3x) + Ce^{-2x}$$

From the initial condition y(0)=1, we have  $1=-\frac{3}{13}+C$ , or  $C=\frac{16}{13}$ , and then

(6-24) 
$$y = \frac{1}{13} (2\sin 3x - 3\cos 3x) + \frac{16}{13} e^{-2x}$$

which is the unique solution for y(0)=1.

Consider the other example of  $1^{st}$ -oreder linear ODE with initial condition, which is given as

(6-25) 
$$y' + \frac{2}{x}y = x^2, \quad y(1) = 2$$

where  $x\neq 0$ . Since  $p(x) = \frac{2}{x}$  and  $q(x) = x^2$ , the integrating factor is

(6-26) 
$$\mu = e^{\int p(x)dx} = e^{2\ln|x|} = x^2, \text{ for } x \neq 0$$

Multiplying (6-25) by  $\mu = x^2$  yields  $x^2y' + 2xy = x^4$ , i.e.,  $\frac{d}{dx}(x^2y) = x^4$ .

Hence,  $x^2y = \frac{1}{5}x^5 + C$  or  $y = \frac{1}{5}x^3 + \frac{C}{x^2}$ . From the initial condition y(1)=2, it can be obtained that  $2 = \frac{1}{5} + C$  or  $C = \frac{9}{5}$ . Therefore, the solution is

(6-27) 
$$y = \frac{1}{5}x^3 + \frac{9}{5x^2}, \quad \text{for } x \neq 0$$

which is a unique solution.

For some linear ODEs, their form may be simple but their solutions cannot be expressed in a closed form. For example,

$$(6-28) y' - xy = 1$$

which seems quite simple; however, its solution is obtained as

(6-29) 
$$y = e^{x^2/2} \int e^{-x^2/2} dx + Ce^{x^2/2}$$

where  $\int e^{-x^2/2} dx$  cannot be written into a closed form.

## **Homogeneous Equations**

A 1<sup>st</sup>-order ODE y' = f(x, y) can be also expressed as the following form M(x, y) + N(x, y)y' = 0, or

(6-30) 
$$y' = f(x, y) = -\frac{M(x, y)}{N(x, y)}$$

If both M(x, y) and N(x, y) are homogeneous functions, which have the same degree n, i.e.,  $M(\lambda x, \lambda y) = \lambda^n M(x, y)$  and  $N(\lambda x, \lambda y) = \lambda^n N(x, y)$  where  $\lambda$  is a factor. For example, the polynomial  $M(x, y) = x^2 + 7xy + 5y^2$  contains there terms of degree 2, i.e., it is a homogeneous function of degree 2. Hence,  $M(\lambda x, \lambda y) = \lambda^2 x^2 + 7\lambda^2 xy + 5\lambda^2 y^2 = \lambda^2 M(x, y)$ . Now, let's change (6-30) into

(6-31) 
$$y' = -\frac{M(x, y)}{N(x, y)} = -\frac{\lambda^n M(x, y)}{\lambda^n N(x, y)} = -\frac{M(\lambda x, \lambda y)}{N(\lambda x, \lambda y)} = f(\lambda x, \lambda y)$$

Let  $\lambda = \frac{1}{x}$ , then  $y' = f\left(1, \frac{y}{x}\right) = -\frac{M(1, y/x)}{N(1, y/x)}$ . For simplicity, it is often simply

written as

$$(6-32) y' = f\left(\frac{y}{x}\right)$$

and called a homogeneous equation for  $x \neq 0$ .

Note that the term "homogeneous equation" used here means the equation is formed by a homogeneous function, which is different to the "homogeneous equation" of an ODE without q(t) on the right hand side.

Let's define  $u = \frac{y}{x}$ , then y = ux and y' = u + xu'. Hence, (6-32) can

be changed into u + xu' = f(u), or

$$\frac{du}{f(u)-u} = \frac{dx}{x}$$

which is an ODE with separable variables. After integrating, we can obtain u and the solution is y=ux.

Consider the 1<sup>st</sup>-order ODE  $xy' = \frac{y^2}{x} - 2y$  for  $x \neq 0$ , which can be

further rewritten as

(6-34) 
$$y' = \frac{y^2 - 2xy}{x^2} = -\frac{M(x, y)}{N(x, y)}$$

with  $M(x, y) = -y^2 + 2xy$  and  $N(x, y) = x^2$ . Both M(x, y) and N(x, y) are homogeneous functions of order 2 and then

(6-35) 
$$y' = \left(\frac{y}{x}\right)^2 - 2\frac{y}{x} = f\left(\frac{y}{x}\right)$$

Define  $u = \frac{y}{x}$ , then y = ux and y' = u + xu'. Hence,  $u + xu' = u^2 - 2u$ , i.e.,

$$xu' = u^2 - 3u$$
, or

$$\frac{du}{u^2 - 3u} = \frac{dx}{x}$$

After integration, we have  $ln|u-3|-ln|u|-ln|x^3|=3C_1$  with  $C_1$  constant. That

means 
$$\frac{u-3}{ux^3} = \pm e^{3C_1}$$
 or

$$(6-37) y = \frac{3x}{1 - Cx^3}$$

where  $C = \pm e^{3C_1}$  and  $x \neq 0$ .

### **Bernoulli Equations**

A 1<sup>st</sup>-order ODE is called Bernoulli equation if it is expressed as the

following form

$$(6-38) y' + p(x)y = r(x)y^{\alpha}$$

in which  $\alpha$  is a real number.

The Bernoulli equation (6-38) is possessed of separable variables if  $\alpha = 1$  and is linear if  $\alpha = 0$ . For the case of  $\alpha \neq 1$ , (6-38) can be transformed to a linear equation by defining

$$(6-39) v = v^{1-\alpha}$$

Its derivative is  $v' = (1 - \alpha)y^{-\alpha}y'$  and from (6-38) we have

(6-40) 
$$v' = (1 - \alpha)y^{-\alpha}(r(x)y^{\alpha} - p(x)y) = (1 - \alpha)(r(x) - p(x)y)$$

or

(6-41) 
$$v' + (1 - \alpha)p(x)v = (1 - \alpha)r(x)$$

which is linear and can be solved by the methods introduced before.

Consider  $y' + xy = 2xy^2$ , which is a Bernoulli equation with  $\alpha = 2$ ,

where 
$$p(x) = x$$
 and  $r(x) = 2x$ . Let  $v = y^{1-\alpha} = y^{-1}$ , then

(6-42) 
$$v' = -y^{-2}y' = -y^{-2}(2xy^2 - xy) = -2x + xv$$

or

$$(6-43) v' - xv = -2x$$

which is a linear ODE. Then, choose  $\mu = e^{\int (-x)tx} = e^{-x^2/2}$  as the integrating factor whose derivative is  $\mu' = -xe^{-x^2/2} = -x\mu$ . Then, multiplying  $\mu$  into (6-43) gets  $\mu v' - \mu xv = -2\mu x$  or  $\mu v' + \mu' v = -2\mu x$ . Hence,

(6-44) 
$$d(\mu v) = (\mu v' + \mu' v)dx = -2\mu x dx$$

which results in

(6-45) 
$$\mu v = \int (-2\mu x)dx + C = -\int e^{-x^2/2}dx^2 + C = 2e^{-x^2/2} + C$$

Hence,  $e^{-x^2/2}y^{-1} = 2e^{-x^2/2} + C$  or

(6-46) 
$$y = \frac{1}{2 + Ce^{x^2/2}}$$

which is the explicit solution of  $y' + xy = 2xy^2$ .

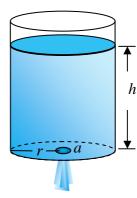
For the example of discharging water through a drain hole at the bottom of a tank, the related ODE is

$$\frac{dh}{dt} = -\frac{a}{\pi r^2} \sqrt{2gh}$$

or

(6-48) 
$$h' = -\frac{a\sqrt{2g}}{\pi r^2} h^{\frac{1}{2}}$$

which is a Bernoulli equation with  $\alpha = \frac{1}{2}$ ,



$$p(x) = 0$$
 and  $r(x) = -\frac{a\sqrt{2g}}{\pi r^2}$ . Let  $v = h^{1-\alpha} = h^{\frac{1}{2}}$ , then

(6-49) 
$$v' = \frac{1}{2}h^{-\frac{1}{2}}h' = \frac{1}{2}h^{-\frac{1}{2}}\left(-\frac{a\sqrt{2g}}{\pi r^2}h^{\frac{1}{2}}\right) = -\sqrt{\frac{g}{2}}\frac{a}{\pi r^2}$$

Hence, 
$$v(t) = -\sqrt{\frac{g}{2}} \frac{a}{\pi r^2} t + C$$
, i.e.,

(6-50) 
$$h(t) = \left(-\sqrt{\frac{g}{2}} \frac{a}{\pi r^2} t + C\right)^2 = \frac{g}{2} \left(\frac{a}{\pi r^2} t - k\right)^2$$

where  $k = C\sqrt{2/g}$  is an arbitrary constant.

### **Riccati Equations**

A 1<sup>st</sup>-order ODE is called Riccati equation if it can be expressed as the following form

(6-51) 
$$y' = p(x)y^2 + q(x)y + r(x)$$

which is not a linear equation. Assume Y(x) is a solution of (6-51) and define

(6-52) 
$$y = Y(x) + \frac{1}{z}$$

Then, the derivative of y is

(6-53) 
$$y' = Y'(x) - \frac{1}{z^2} z'$$

Substituing (6-52) and (6-53) into (6-51) obtains

(6-54) 
$$Y' - \frac{1}{z^2}z' = p(x)\left(Y + \frac{1}{z}\right)^2 + q(x)\left(Y + \frac{1}{z}\right) + r(x)$$
$$= p(x)Y^2 + q(x)Y + r(x) + p(x)\left(2\frac{Y}{z} + \frac{1}{z^2}\right) + \frac{1}{z}q(x)$$

Since Y(x) is a solution of (6-51), we know that  $Y' = p(x)Y^2 + q(x)Y + r(x)$ .

Hence, (6-54) is further simplified as  $-\frac{1}{z^2}z' = p(x)\left(2\frac{Y}{z} + \frac{1}{z^2}\right) + \frac{1}{z}q(x)$ , or

(6-55) 
$$z' + (q(x) + 2p(x)Y(x))z = -p(x)$$

which is a linear ODE and can be solved by the methods introduced before.

Consider  $y' = xy^2 - \left(2x + \frac{1}{x}\right)y + x + \frac{1}{x}$  for x > 0, which is a Riccati

equation with p(x) = x,  $q(x) = -\left(2x + \frac{1}{x}\right)$  and  $r(x) = x + \frac{1}{x}$ . It can be found

that Y(x)=1 is a solution; hence, from (6-52) we let

(6-56) 
$$y = Y(x) + \frac{1}{z} = 1 + \frac{1}{z}$$

and from (6-55), we achieve the linear equation as

$$(6-57) z' - \frac{1}{x}z = -x$$

Further choose the integrating factor as

(6-58) 
$$\mu = e^{\int \left(-\frac{1}{x}\right) dx} = e^{-\ln x} = x^{-1}$$

whose derivative is  $\mu' = -x^{-2} = -\frac{\mu}{x}$ . After multiplying  $\mu$  into (6-57), it can be

obtained that  $\mu z' - \frac{1}{x}z\mu = -x\mu$  or  $\frac{d}{dx}(\mu z) = -1$ . Clearly, the result can be

found as  $\mu z = -x + C$  with C constant. Hence,

$$(6-59) z = -x^2 + Cx$$

and then the solution in (6-56) is

(6-60) 
$$y = 1 + \frac{1}{z} = \frac{-x^2 + Cx + 1}{-x^2 + Cx}$$

which is an explicit solution.

Further consider a free falling object with mass m. If it encounters a quadratic friction, then the dynamic model can be described as

$$(6-61) mv'(t) = mg - \beta v^2(t)$$

where v(t) is the velocity and  $-\beta v^2(t)$  is the quadratic friction. It can be rewritten as

(6-62) 
$$v' = -\frac{\beta}{m}v^2 + g = p(t)v^2 + q(t)v + r(t)$$

which is a Riccati equation with  $p(t) = -\frac{\beta}{m}$ , q(t) = 0 and r(t) = g. First,

find a solution, which is  $Y(t) = \sqrt{\frac{mg}{\beta}}$  and let

(6-63) 
$$v = Y(x) + \frac{1}{z} = \sqrt{\frac{mg}{\beta}} + \frac{1}{z}$$

From (6-55), we have the following linear ODE

$$(6-64) z' - 2\sqrt{\frac{\beta g}{m}}z = \frac{\beta}{m}$$

and the solution is

(6-65) 
$$z = ke^{2\sqrt{\frac{\beta g}{m}t}} - \frac{1}{2}\sqrt{\frac{\beta}{mg}}$$

Hence,

(6-66) 
$$v = \sqrt{\frac{mg}{\beta}} + \left(ke^{2\sqrt{\frac{\beta g}{m}}t} - \frac{1}{2}\sqrt{\frac{\beta}{mg}}\right)^{-1}$$

which is an explicit solution. If the initial velocity is zero, i.e., v(0) = 0. Then,

from (6-66), we obtain 
$$\sqrt{\frac{mg}{\beta}} + \left(k - \frac{1}{2}\sqrt{\frac{\beta}{mg}}\right)^{-1} = 0$$
, or  $k = -\frac{1}{2}\sqrt{\frac{\beta}{mg}}$  and the

solution in (6-65) becomes

(6-67) 
$$v(t) = \sqrt{\frac{mg}{\beta}} \left( \frac{e^{\sqrt{\frac{\beta g}{m}t}} - e^{-\sqrt{\frac{\beta g}{m}t}}}{e^{\sqrt{\frac{\beta g}{m}t}} + e^{-\sqrt{\frac{\beta g}{m}t}}} \right) = \sqrt{\frac{mg}{\beta}} \tanh \sqrt{\frac{\beta g}{m}t}$$

As  $t \to \infty$ , we have the terminal velocity  $v(\infty) = \sqrt{\frac{mg}{\beta}}$ .