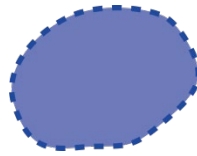


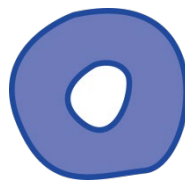
## §16.3 The Fundamental Theorem for Line Integrals

\*名詞介紹：

- (i) smooth curves; piecewise smooth curves (= paths).
- (ii) closed curves : initial point = terminal point.
- (iii) open region :



- (iv) connected :



(yes)



(no)

- (v) simple curve : a curve that does not intersect itself anywhere between its endpoints.



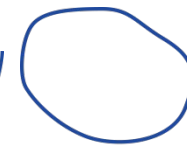
not simple,  
closed



not simple,  
not closed



simple,  
not closed



simple,  
closed

(no)

(yes)

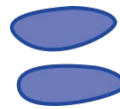
- (vi) Simply connected region : No hole + No separate pieces.



(yes)



(no)



(no)

- (vii)  $\int_C \mathbf{F} \cdot d\mathbf{r}$  is independent of path :

$$\int_{C_1} \mathbf{F} \cdot d\mathbf{r} = \int_{C_2} \mathbf{F} \cdot d\mathbf{r} \text{ for any } C_1, C_2 \text{ having the same initial points and the same terminal points.}$$

## Line integral 的基本定理

Recall :

$$\int_a^b F'(x) dx = F(b) - F(a) \quad (\text{微積分基本定理, FTC})$$

**Theorem (16.3.2)(梯度定理)** Let  $\mathbf{F} = \langle P, Q \rangle$ .

- 已知 :
- (i)  $\mathbf{F} = \nabla f$  (保守場).
  - (ii)  $\nabla f$  is continuous on  $C$ .
  - (iii)  $C$  : (piecewise) smooth curve  $\mathbf{r}(t)$ ,  $a \leq t \leq b$ .

結論 : 
$$\int_C \mathbf{F} \cdot d\mathbf{r} = \int_C \nabla f \cdot d\mathbf{r} = f(\mathbf{r}(b)) - f(\mathbf{r}(a)).$$

**Proof :**

$$\begin{aligned} n=3 \quad \int_C \mathbf{F} \cdot d\mathbf{r} &= \int_a^b \nabla f(\mathbf{r}(t)) \cdot \mathbf{r}'(t) dt \\ &= \int_a^b \left[ f_x \frac{dx}{dt} + f_y \frac{dy}{dt} + f_z \frac{dz}{dt} \right] dt \\ &= \int_a^b \frac{d}{dt} (f(\mathbf{r}(t))) dt \\ \text{FTC} \swarrow &= f(\mathbf{r}(b)) - f(\mathbf{r}(a)). \end{aligned}$$

$n=2$  : Similar.

**Example 1:**  $\mathbf{F}(x, y) = \left\langle \frac{1}{2}xy, \frac{1}{4}x^2 \right\rangle$   $C_1 : y = x$ ;  $C_2 : x = y^2$ ;  $C_3 : y = x^3$ ;

起點 :  $(0, 0)$  , 終點 :  $(1, 1)$  Compute  $\int_{C_i} \mathbf{F} \cdot d\mathbf{r}$ ,  $i = 1, 2, 3$ .

Solution :  $\mathbf{F} = \nabla f$ , where  $f(x, y) = \frac{x^2}{4}y$ .

$$\Rightarrow \int_{C_i} \mathbf{F} \cdot d\mathbf{r} = f(1, 1) - f(0, 0) = \frac{1}{4} \quad \text{for } i = 1, 2, 3.$$

**Theorem (16.3.3)**  $\int_C \mathbf{F} \cdot d\mathbf{r}$  is independent of path in  $D \Leftrightarrow \int_C \mathbf{F} \cdot d\mathbf{r} = 0$   
for every closed path  $C$  in  $D$ .

**Theorem (16.3.4)** 已知： (i)  $\mathbf{F}: D \subset \mathbb{R}^n \rightarrow \mathbb{R}^n$ ,  $n = 2, 3$ ,  $D$ : open and connected.

(ii)  $\mathbf{F}$ : continuous on  $D$ .

結論：  $\int_C \mathbf{F} \cdot d\mathbf{r}$  is independent of path in  $D$ .

$\Updownarrow$

$\mathbf{F}$  is conservative.

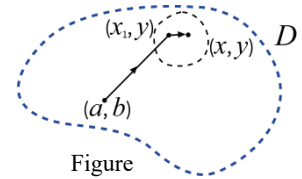
**Proof:** ( $\Leftarrow$ ) Trivial.

( $\Rightarrow$ ) Constructive proof: 實際找一個 potential function  $f$  s.t.  $\nabla f = \mathbf{F}$ .

(i)  $n = 2$  ( $n = 3$  can be similarly proved):

$$\text{Let } f(x, y) = \int_C \mathbf{F} \cdot d\mathbf{r},$$

where  $C$  is a path in  $D$  with a fixed initial point  $(a, b)$  and terminal point  $(x, y)$ .



Figure

(ii)  $f(x, y)$  is well-defined. (What? and Why?)

(iii) Find a particular  $C$ :

Since  $D$  is open,  $\exists (x_1, y) \in D$  with  $x_1 < x$ . Let

$C$  = a path  $C_1 \in D$  from  $(a, b)$  to  $(x_1, y)$  followed by the horizontal line segment  $C_2$  from  $(x_1, y)$  to  $(x, y)$  (See above Figure).

(iv) Claim  $\nabla f = \mathbf{F}$ . Let  $\mathbf{F} = \langle M, N \rangle$ .

$$\begin{aligned} f(x, y) &= \int_C \mathbf{F} \cdot d\mathbf{r} = \int_{C_1} \mathbf{F} \cdot d\mathbf{r} + \int_{C_2} \mathbf{F} \cdot d\mathbf{r} \\ &= \int_{C_1} \mathbf{F} \cdot d\mathbf{r} + \int_{C_2} M dx + N dy \quad x = t \\ &= \int_{C_1} \mathbf{F} \cdot d\mathbf{r} + \int_{x_1}^x M(t, y) dt. \quad \text{Here } dy = 0 \text{ (} C_2 \text{: 水平線段)} \end{aligned}$$

$$\frac{\partial f}{\partial x} = 0 + M(x, y). \quad \left( \int_C \mathbf{F} \cdot d\mathbf{r} \text{ 是和 } x \text{ 無關的相對常數} \right)$$

Similar Construction (how?), we have

$$\frac{\partial f}{\partial y} = N(x, y).$$

有無檢查  $\mathbf{F}$  是否保守場的方法：

$$n = 2$$

已知： (i)  $D$  (定義域) : open simply-connected region.

(ii)  $\mathbf{F} = \langle M, N \rangle$ :  $M, N$ : continuous first-order partial derivatives.

結論：  $\mathbf{F}$  is conservative on  $D \Leftrightarrow \frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$ .

( $\Rightarrow$ ) Clairaut's Theorem.

( $\Leftarrow$ ) Green's Theorem (§16.4).

$$n = 3 \quad \mathbf{F} = \langle M, N, P \rangle$$

同  $n = 2$  類似的已知.

結論：  $\mathbf{F}$  is conservative on  $D \Leftrightarrow \text{Curl } \mathbf{F} = \mathbf{0}$  for all points in  $D$ .

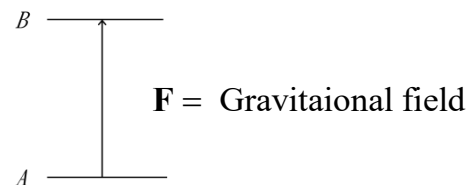
**Theorem (Conservation of Energy)** : In a conservative vector field, the sum of its potential energy and its kinetic energy remains a constant at any point. This is the reason why the vector field is called conservative.

**Proof :**

(i) Let  $\mathbf{F} = \nabla f$

$P(A)$  = 位能 at  $A$  點 =  $-f(A)$  (why?)

$K(A)$  = 動能 at  $A$  點 =  $\frac{1}{2}m\|\mathbf{r}'(A)\|^2$ .



Wanted :  $P(A) + K(A) = P(B) + K(B)$ .

$$\int_A^B \mathbf{F} \cdot d\mathbf{r} = f(B) - f(A) = P(A) - P(B).$$

加速度

$$\mathbf{F} = m\mathbf{a} = m\mathbf{r}''(t)$$

||

$$\int_A^B m\mathbf{r}'' \cdot \mathbf{r}' dt = \frac{1}{2}m \int_A^B \frac{d}{dt} \|\mathbf{r}'(t)\|^2 = \frac{1}{2}m(\|\mathbf{r}'(B)\|^2 - \|\mathbf{r}'(A)\|^2) = K(B) - K(A).$$

$$\Rightarrow P(A) + K(A) = P(B) + K(B).$$